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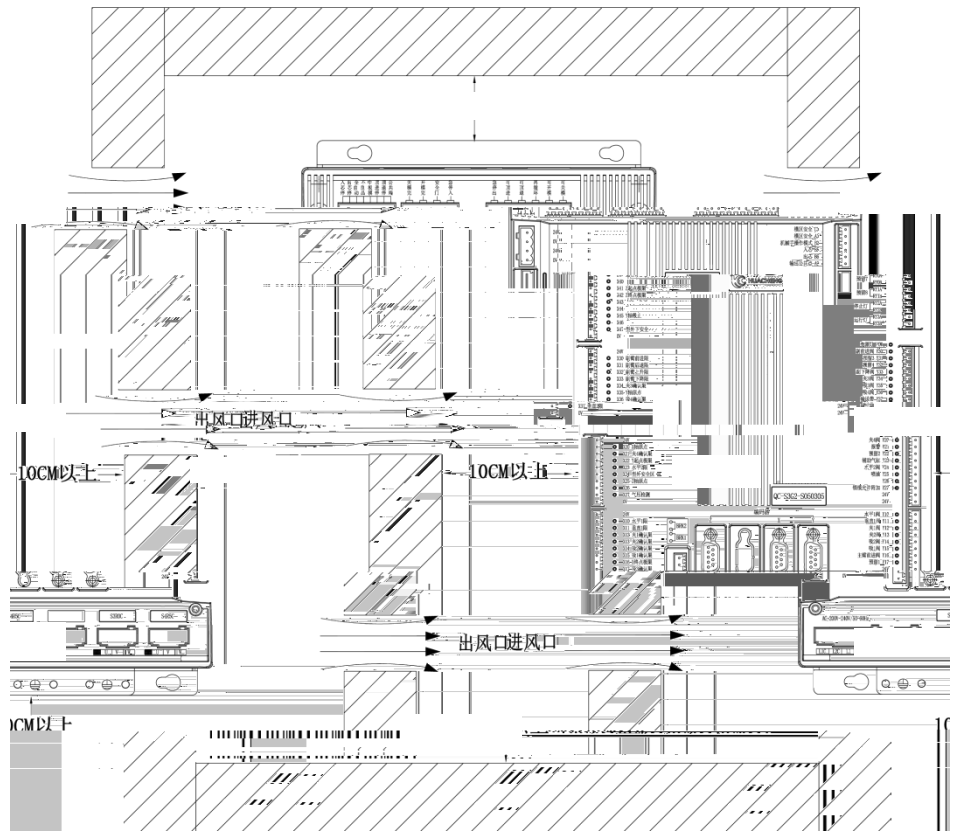
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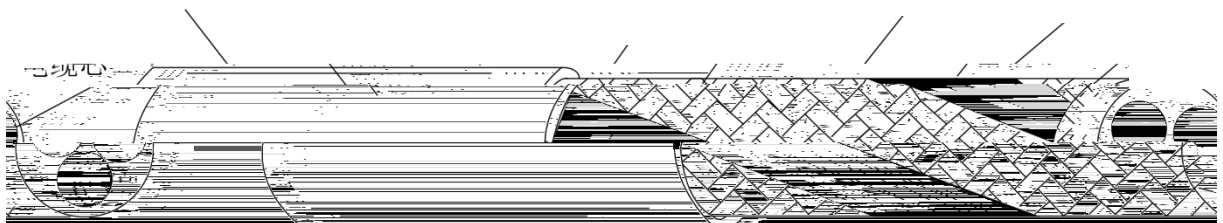
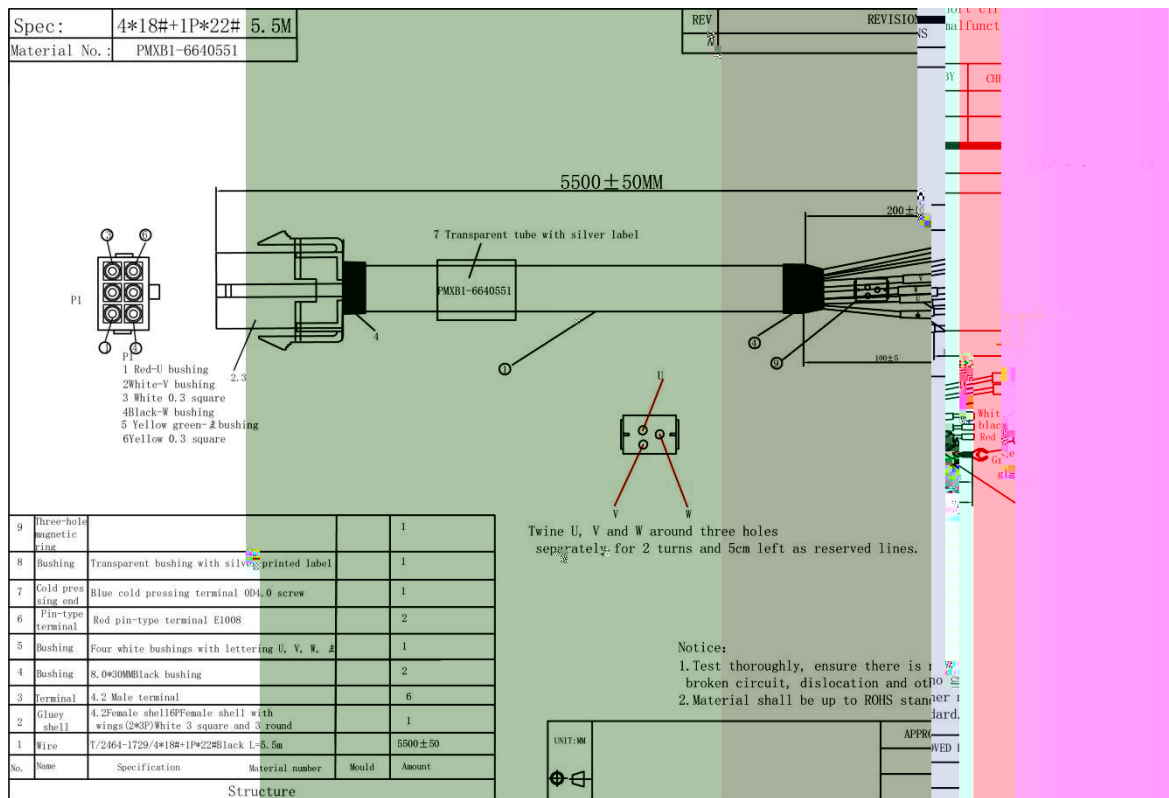


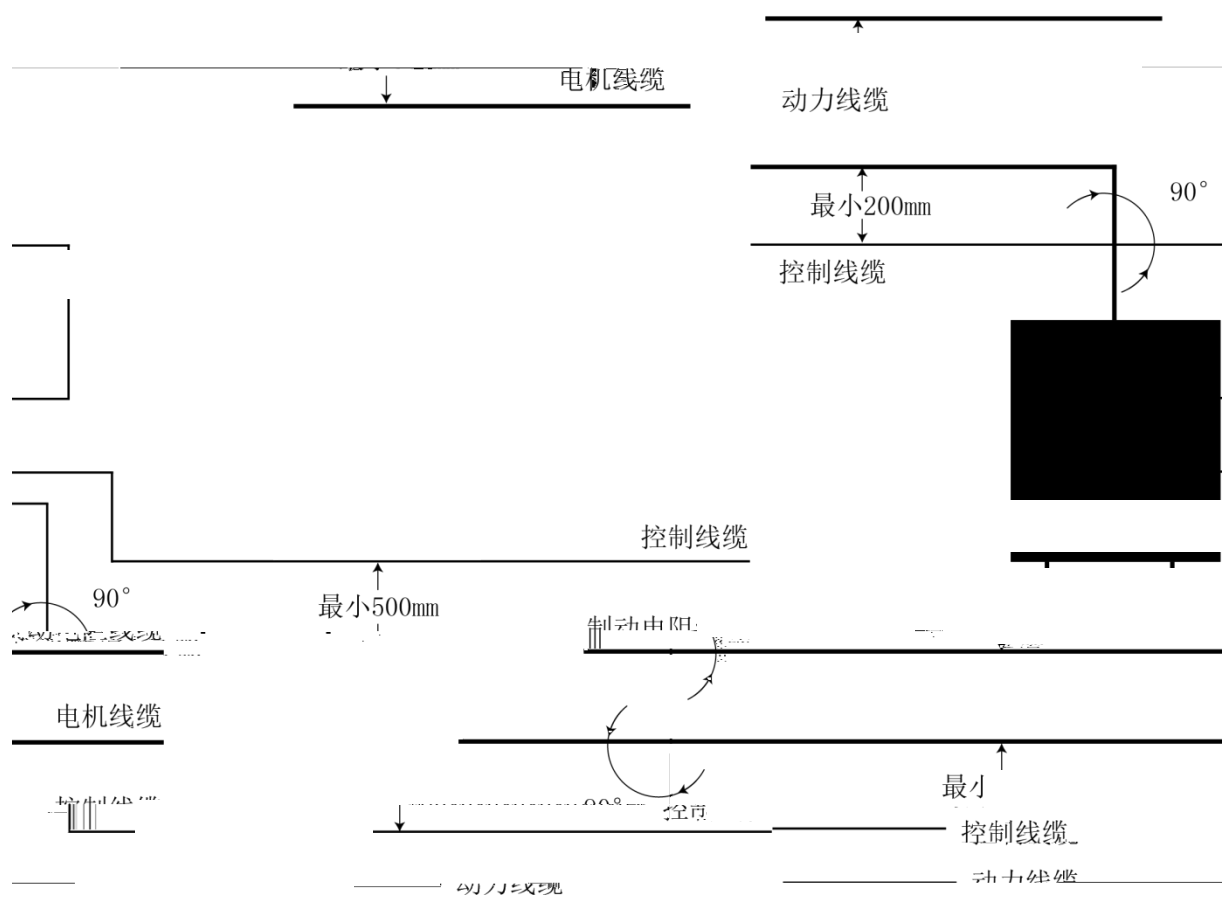


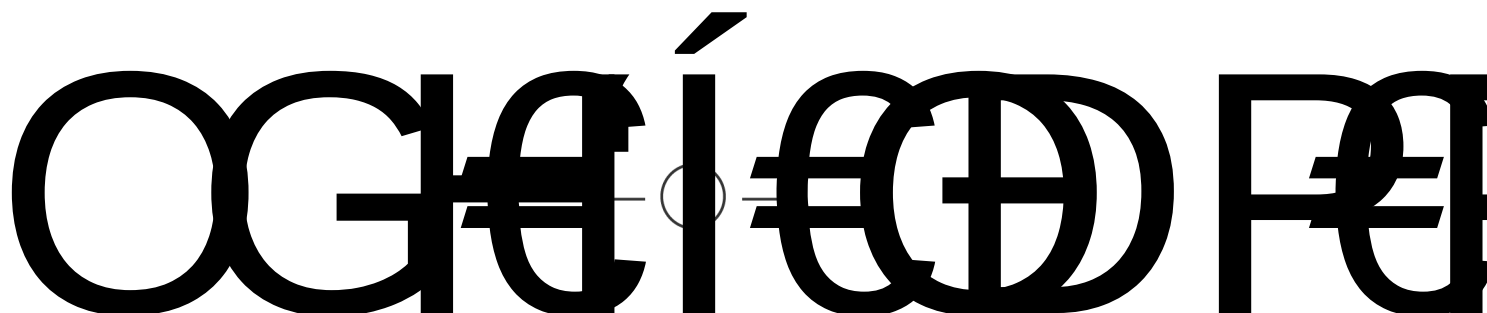
	

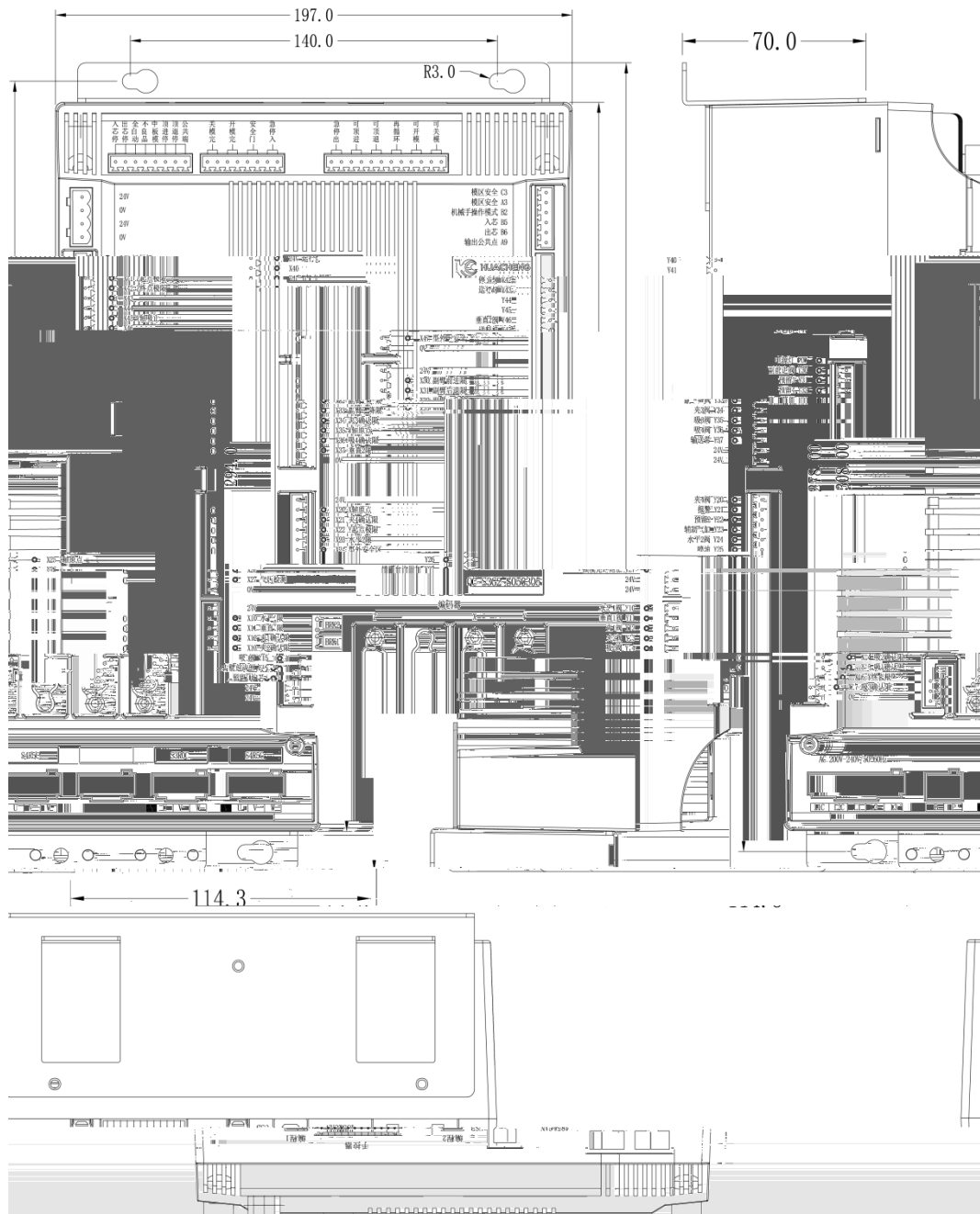
	
	

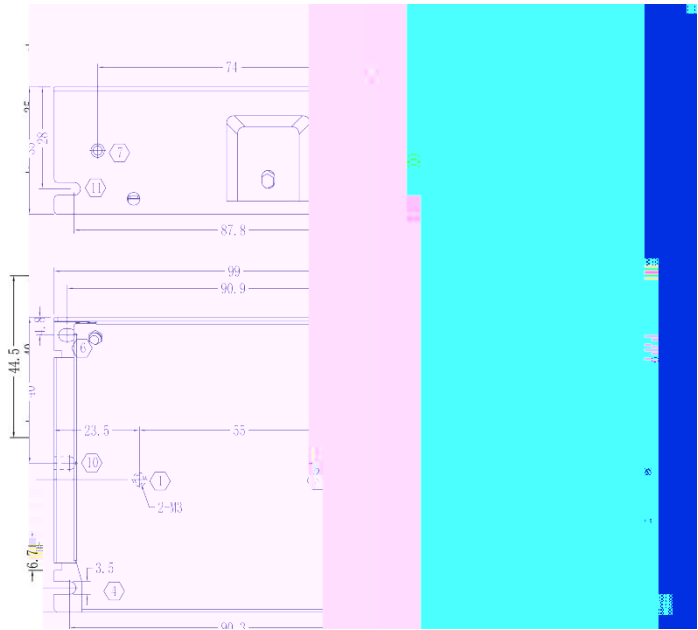


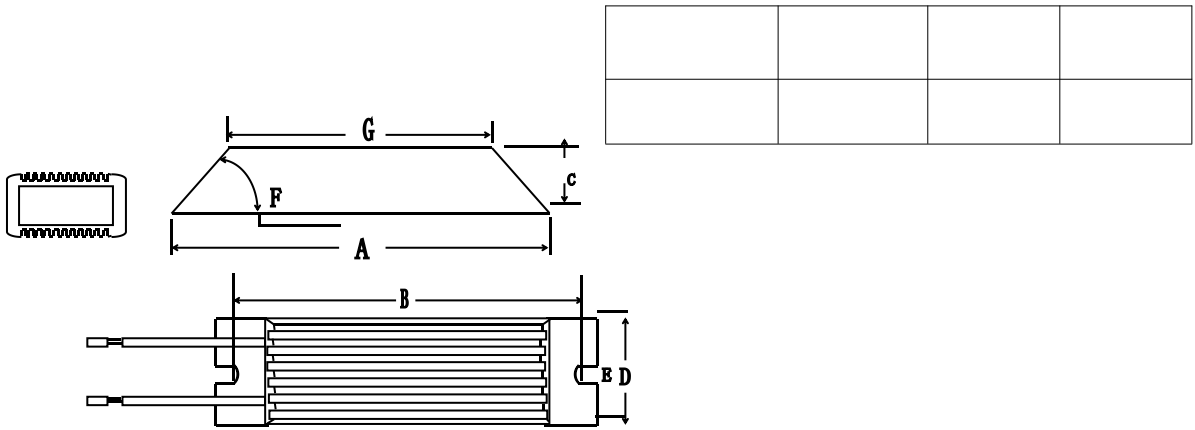


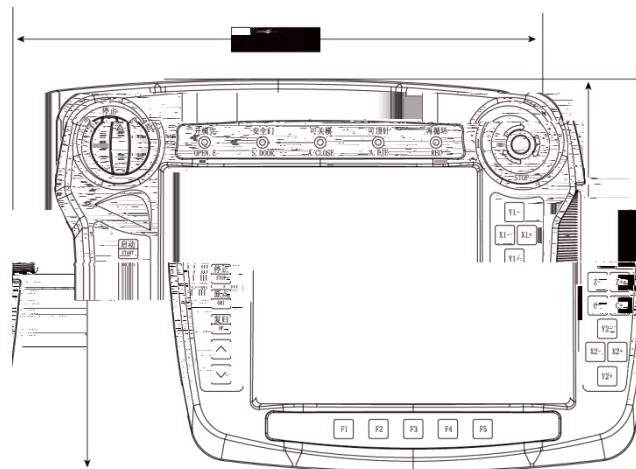


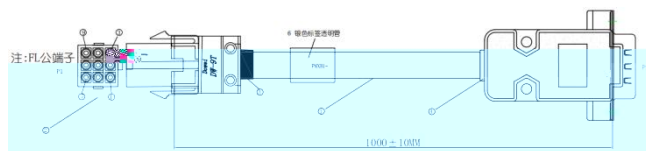




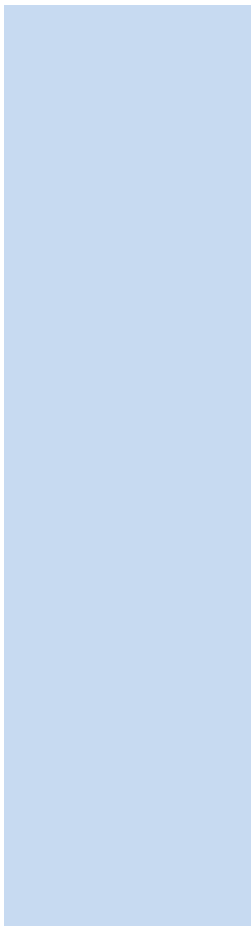


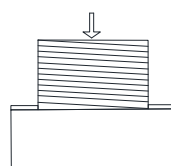
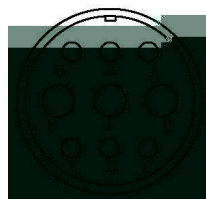
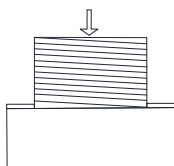
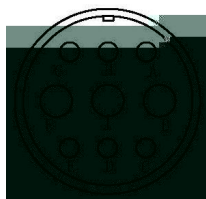


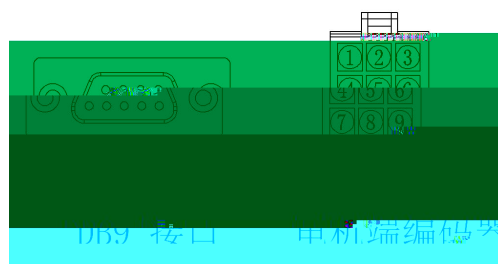




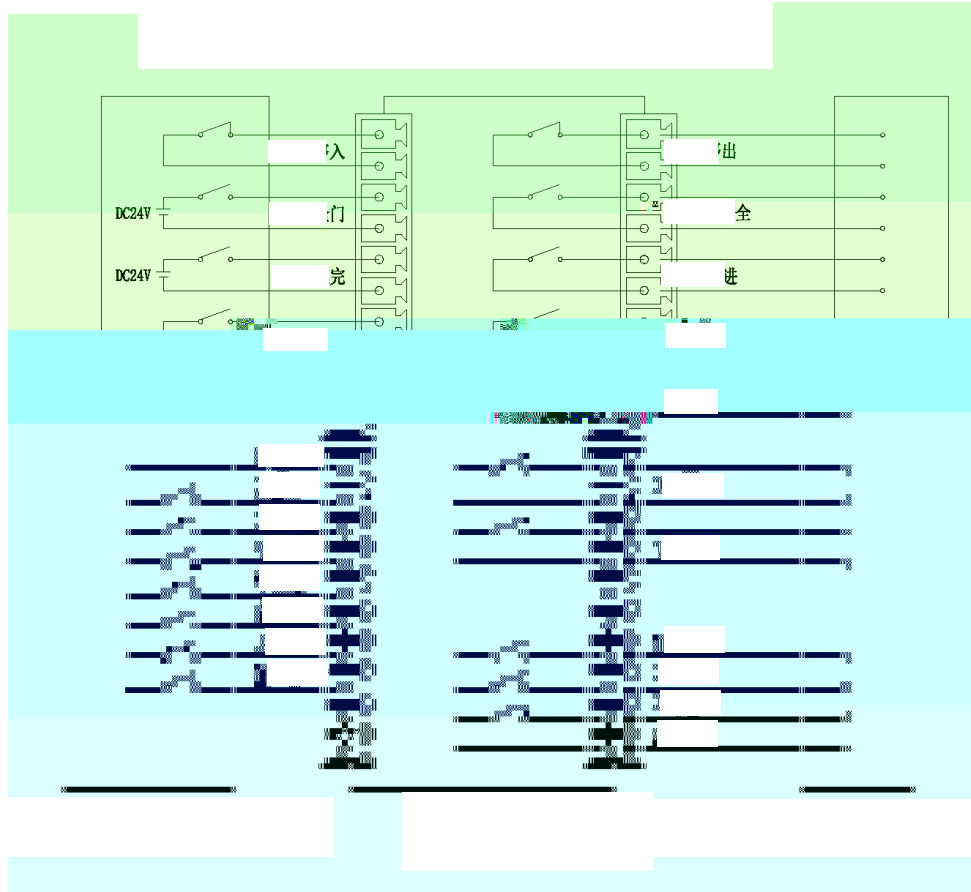
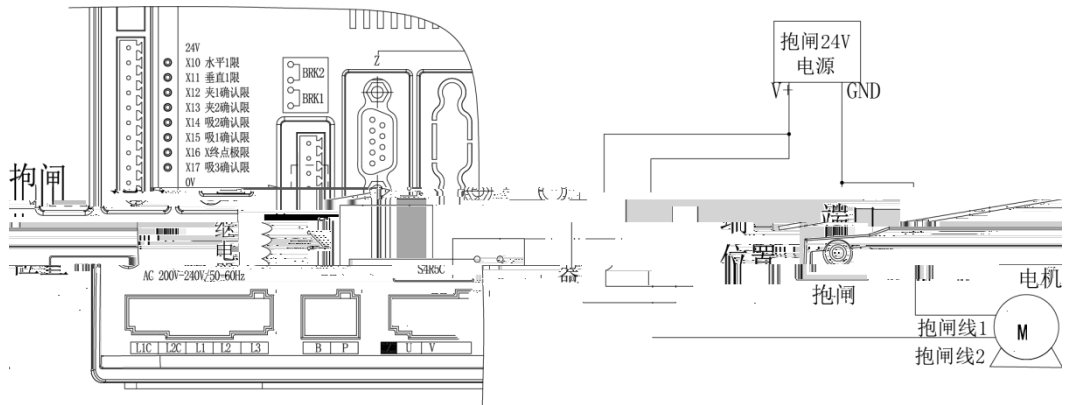
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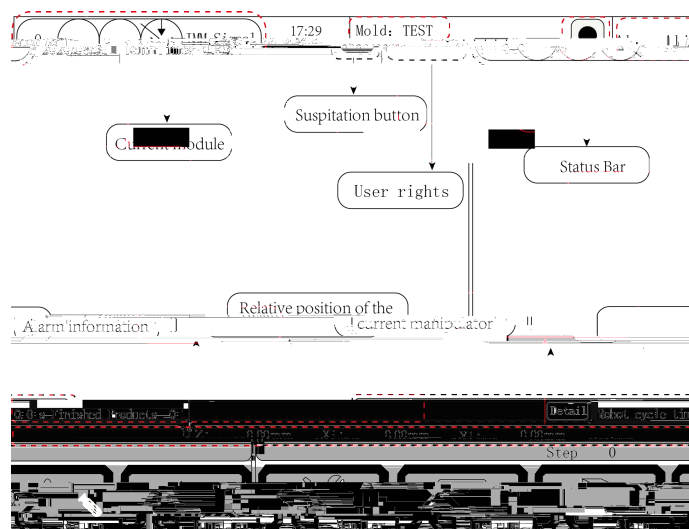
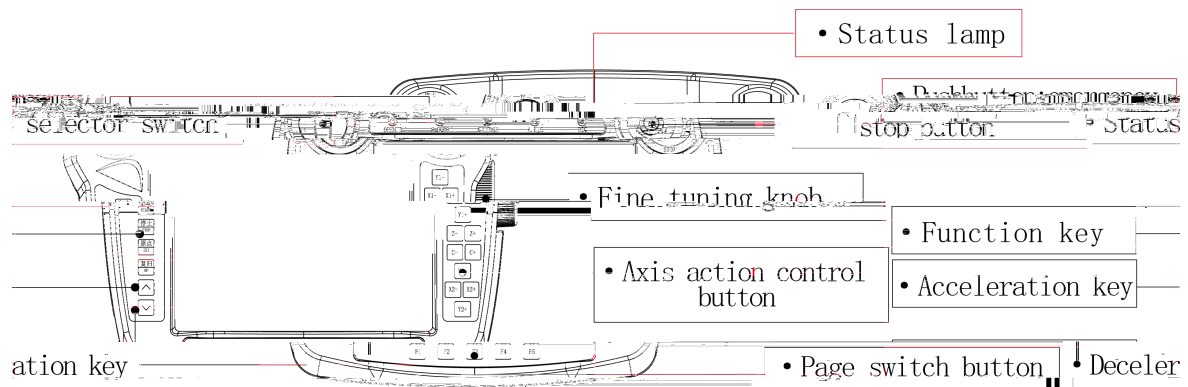






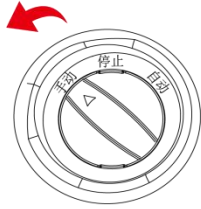
DB9 接口 串机端编码头







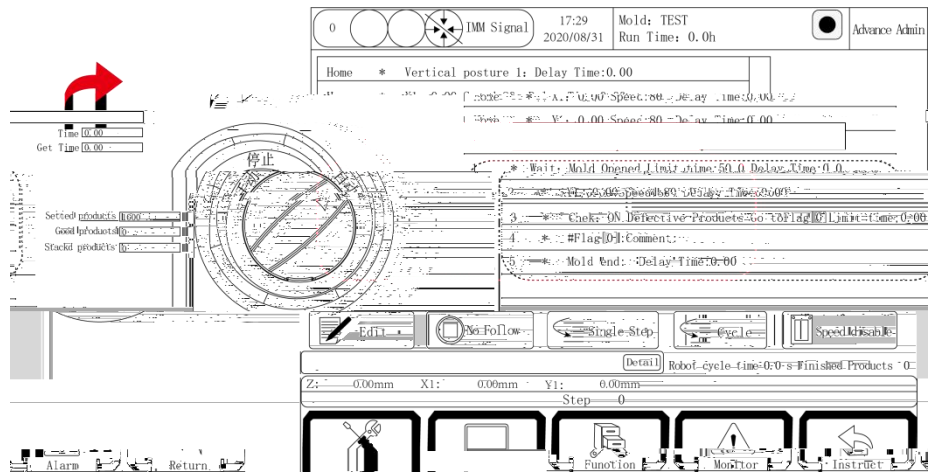


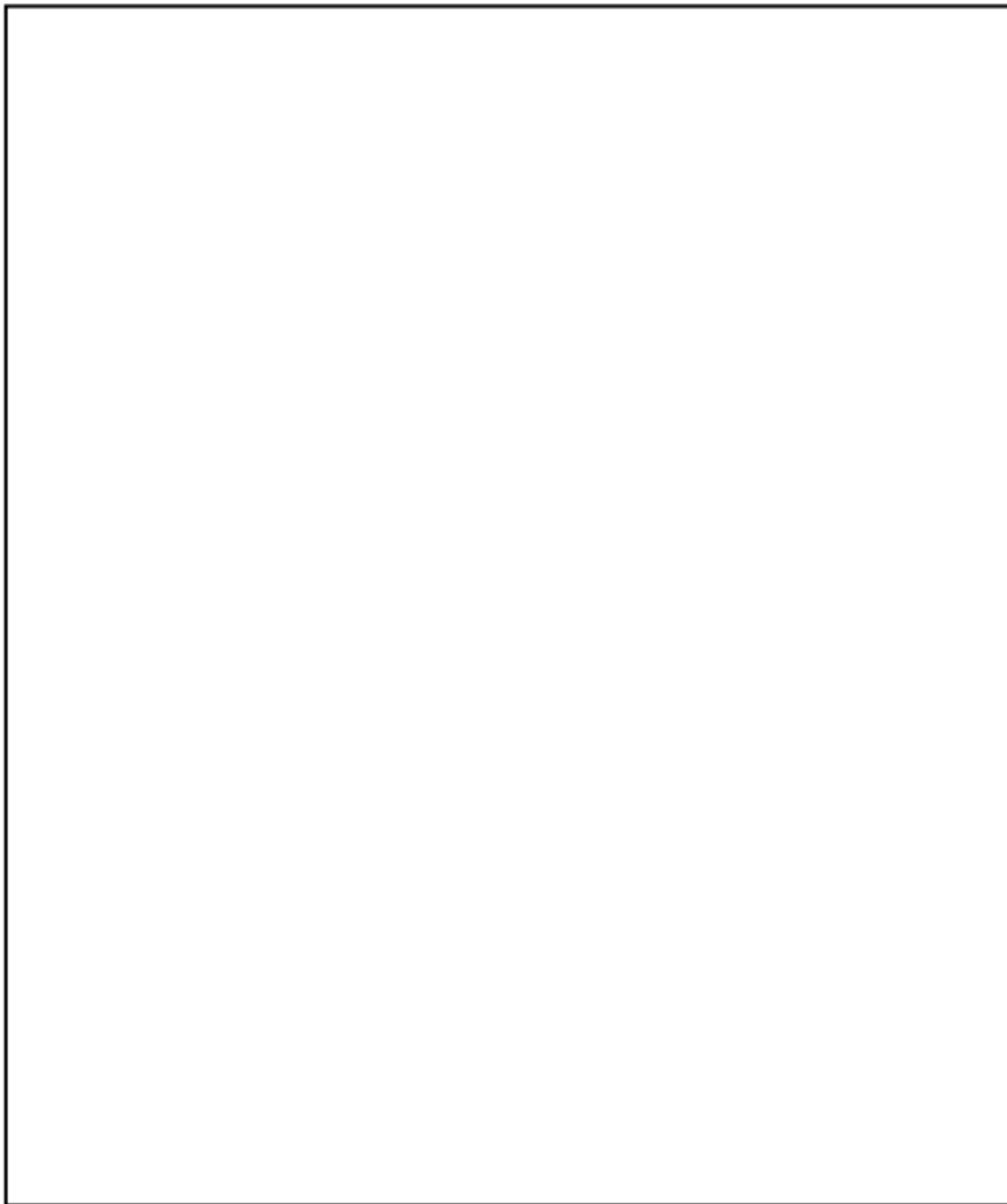


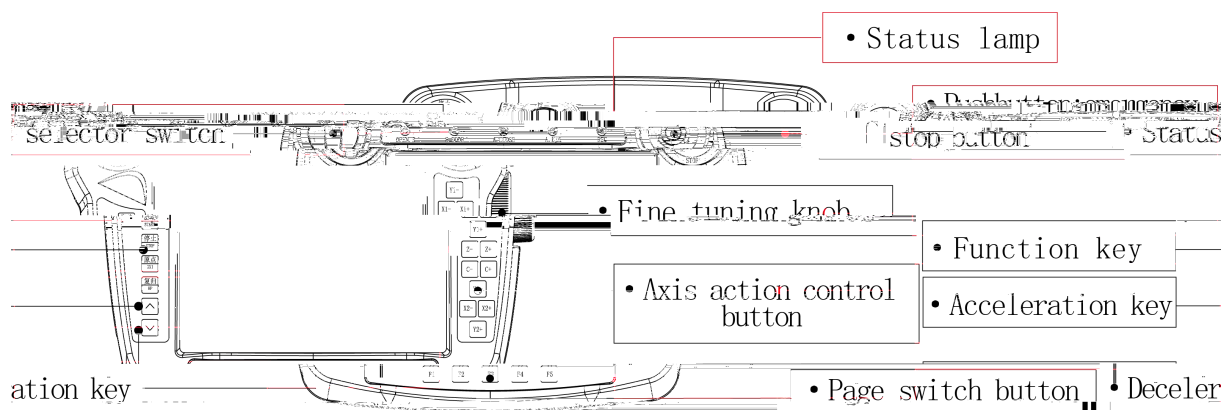
0		IMM Signal	17:29 2020/08/31	Mold: TEST Run Time: 0.0h		Advance Admin
Manual						
Fixture 1 ☐		ON	☐	OFF	Fixture 3 ☐	
					ON	
					OFF	
Fixture 2 ☐		ON	☐	OFF	Fixture 4 ☐	
					ON	
					OFF	
		Fixture		Sucker	Reserve	Manipulator 1/0
Detail						
Robot cycle time 0.0 s Finished Products 0						
Z:	0.00mm	X1:	0.00mm	Y1:	0.00mm	
Step 0						
Function	Monitor	Instruct	Alarm	Return		

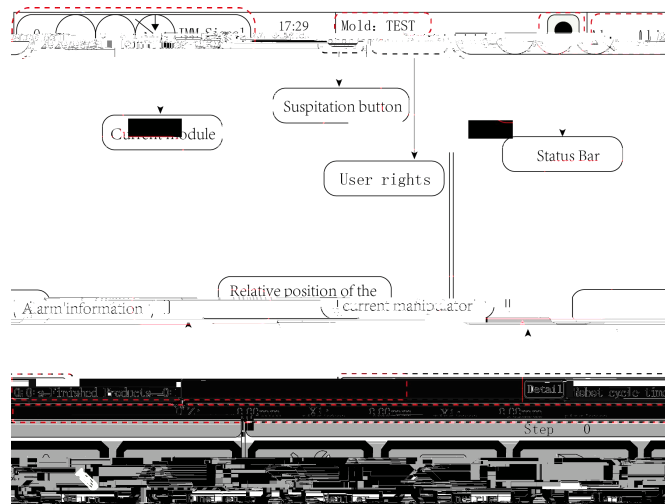
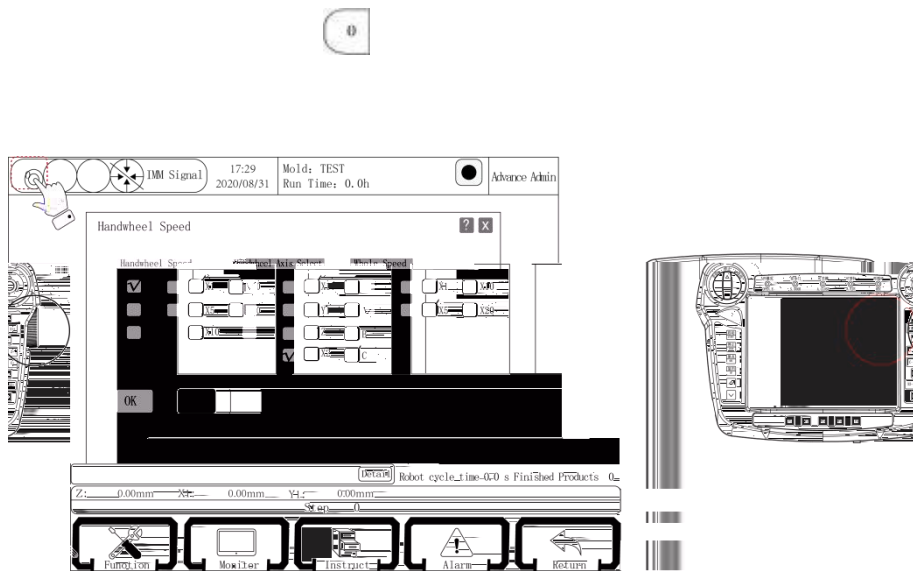




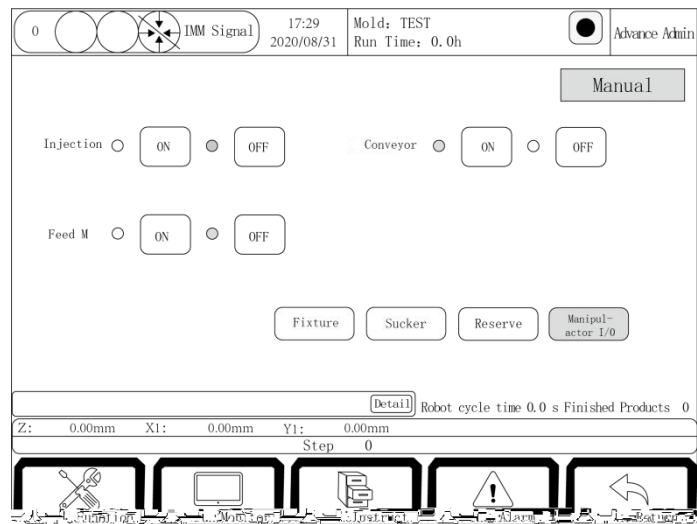
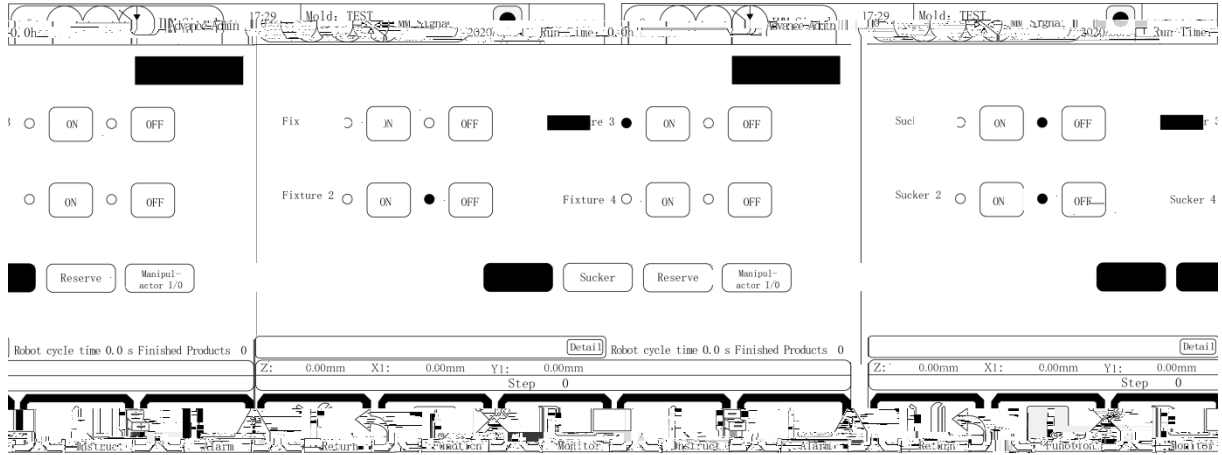


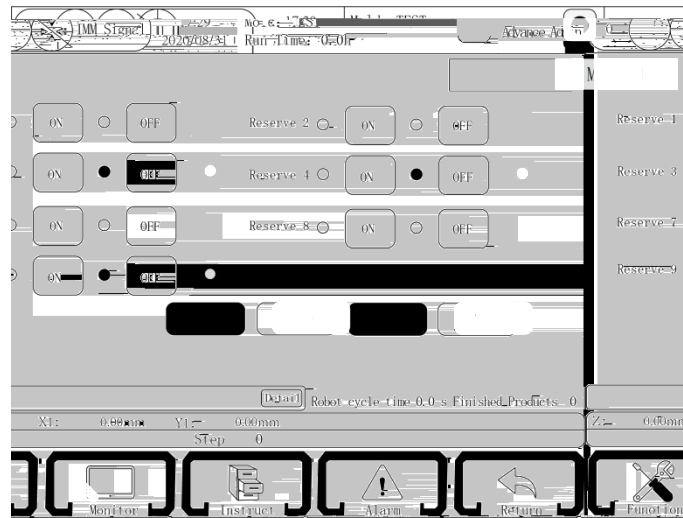




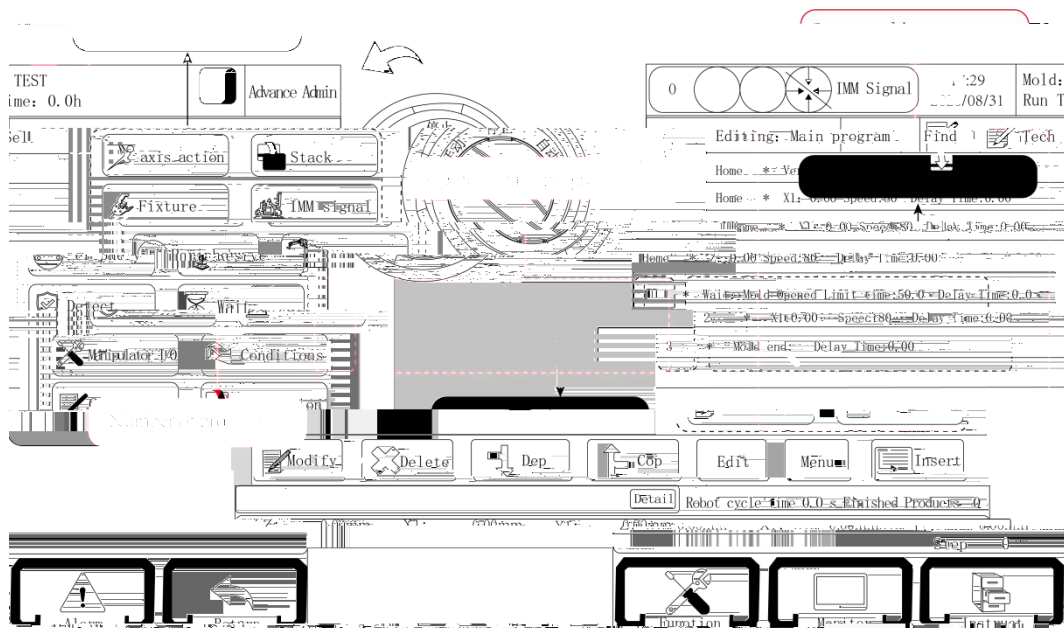


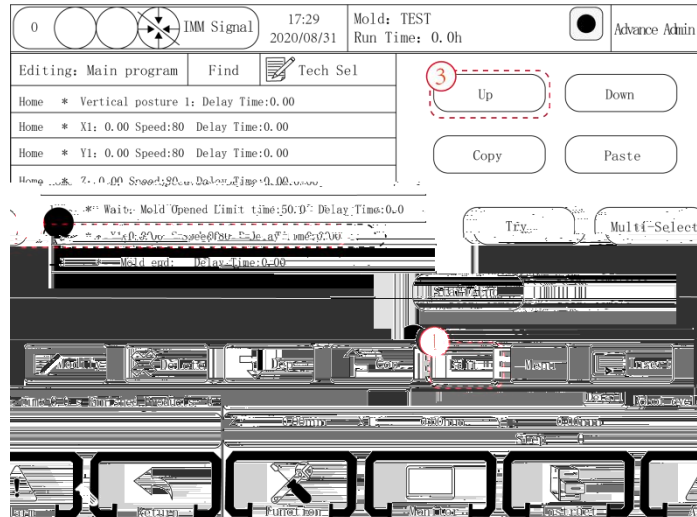




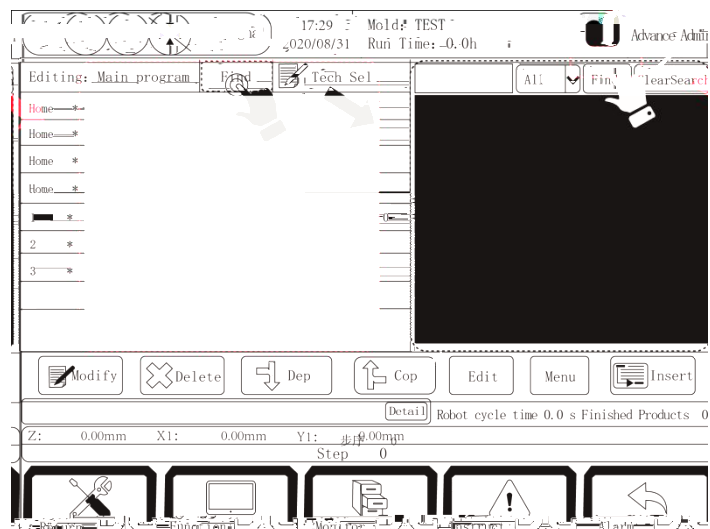


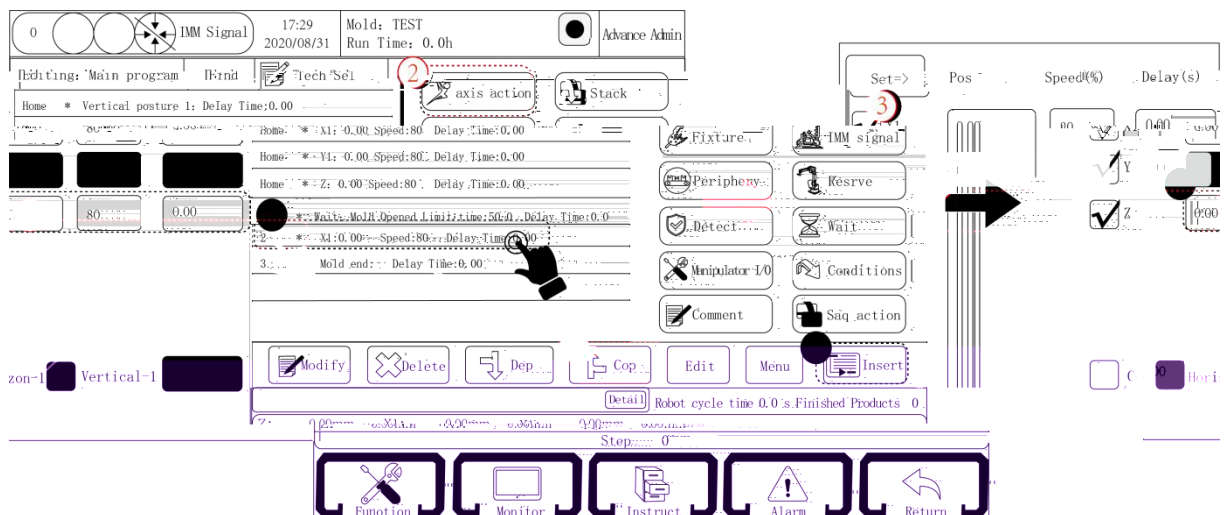
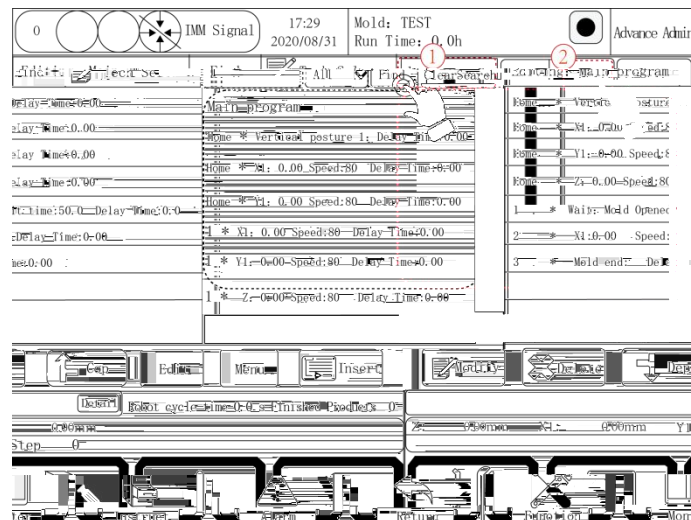
Warn:





Warn:





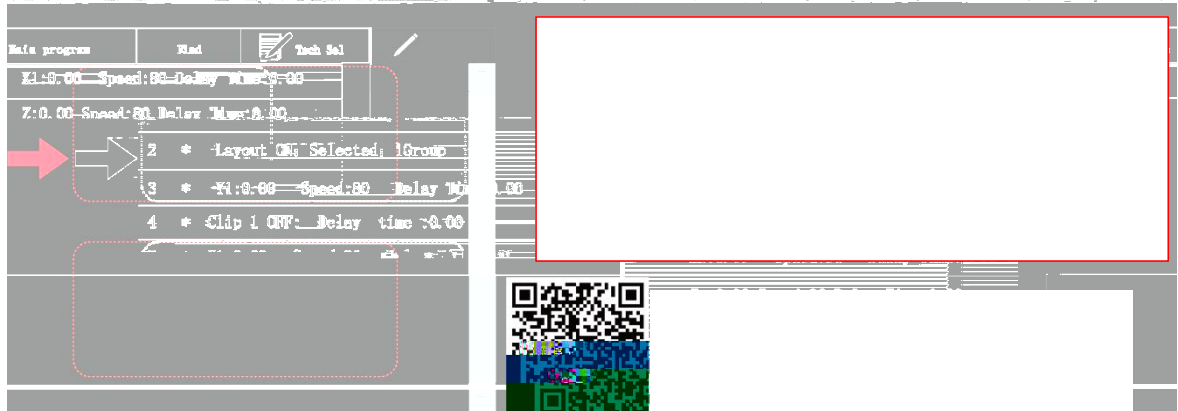
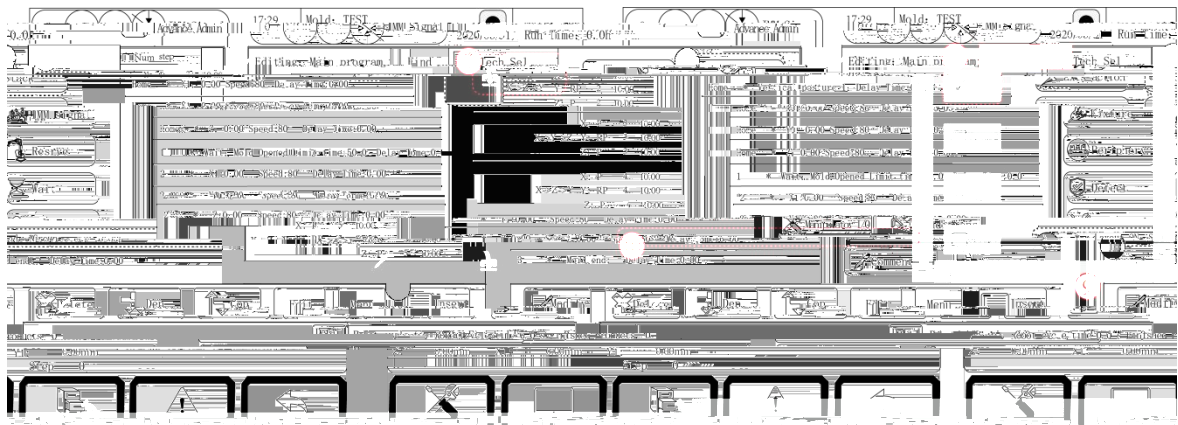
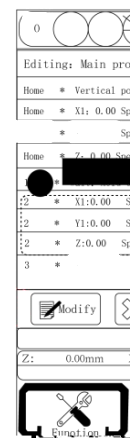
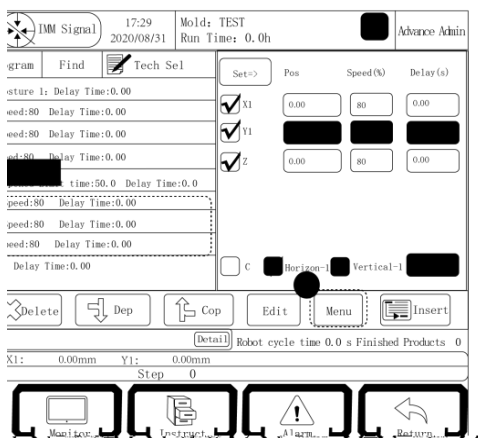
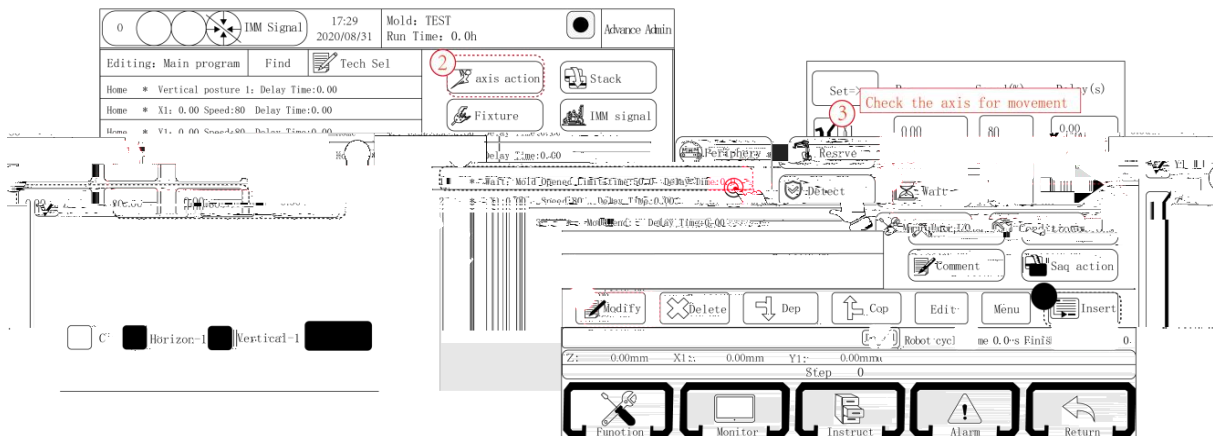
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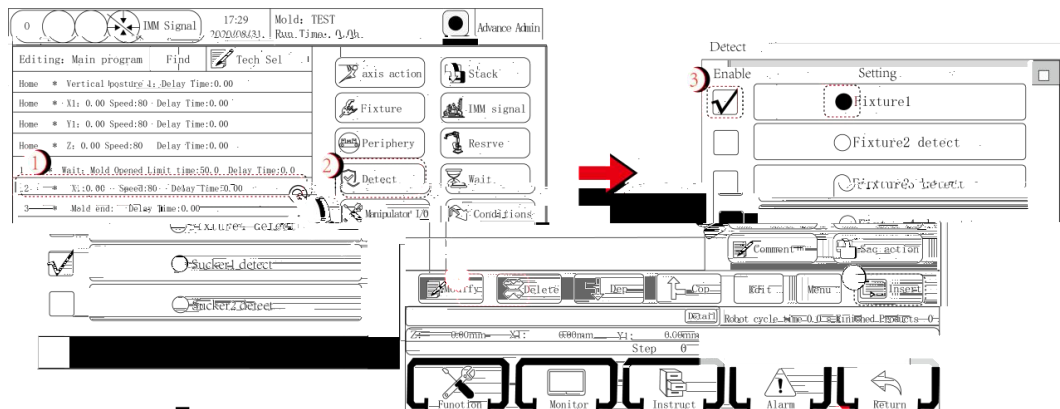
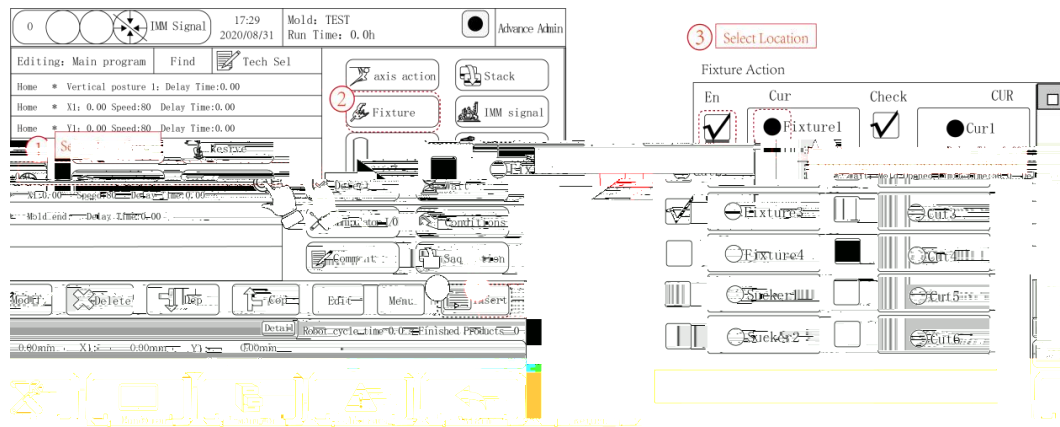
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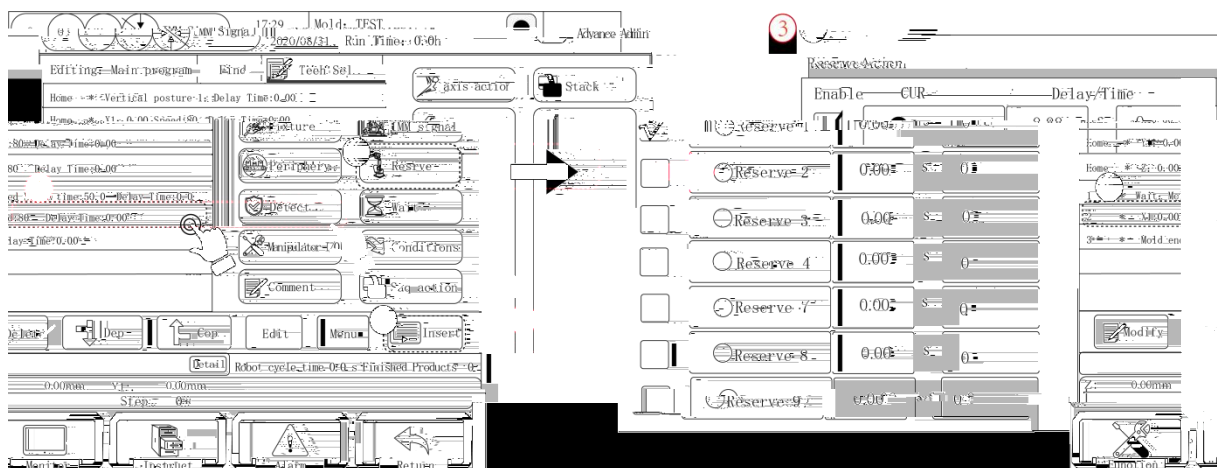
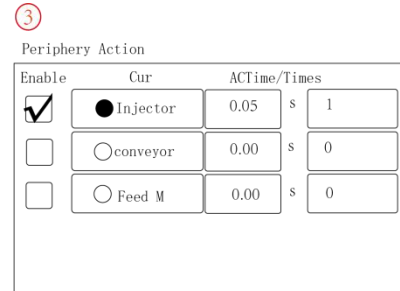
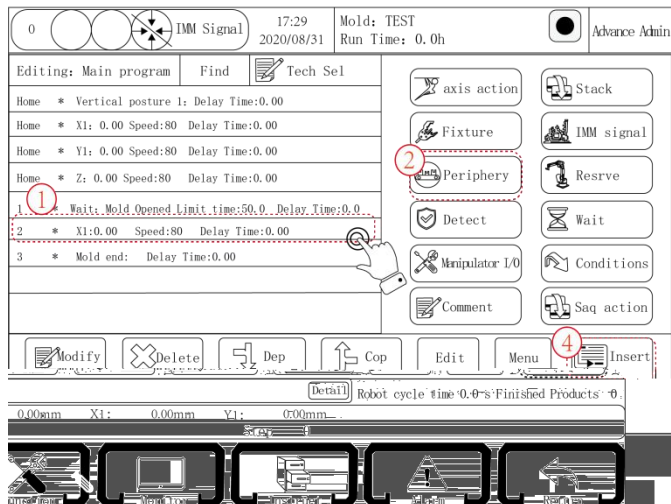
BỐ K

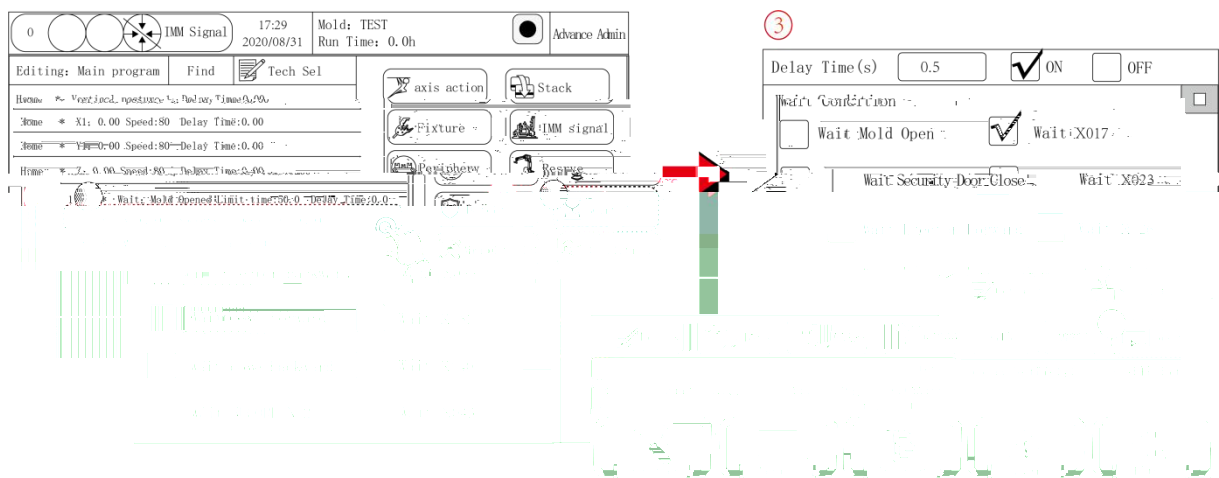


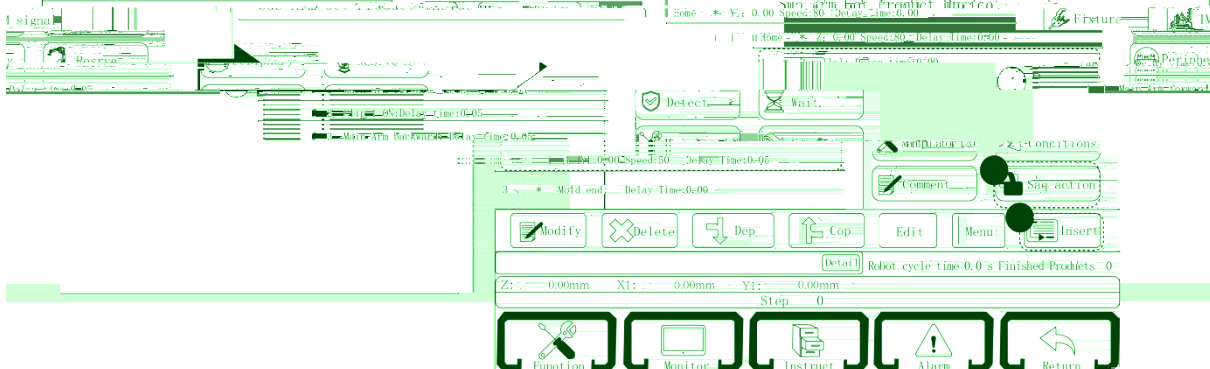


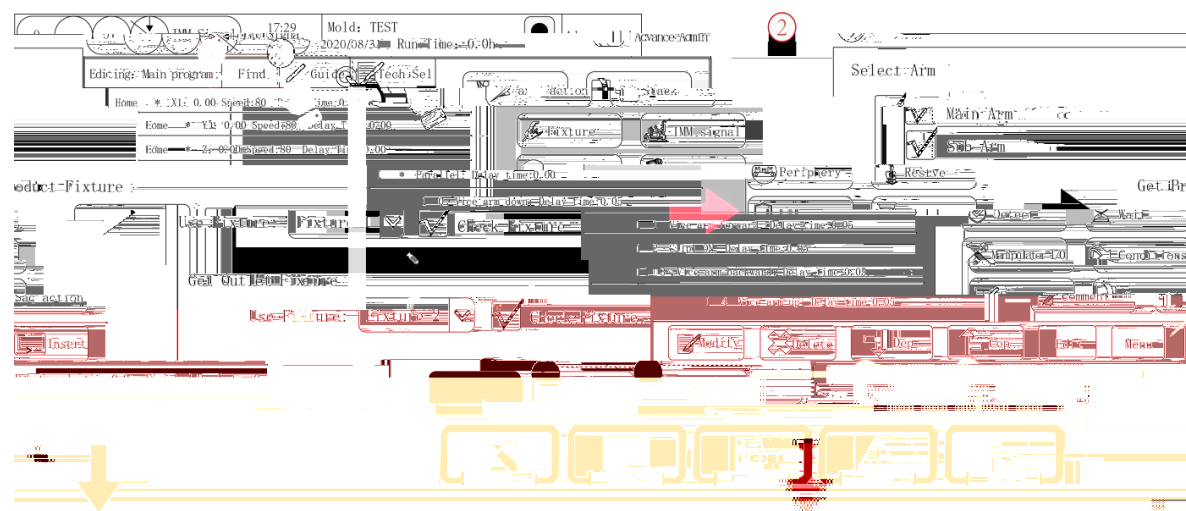
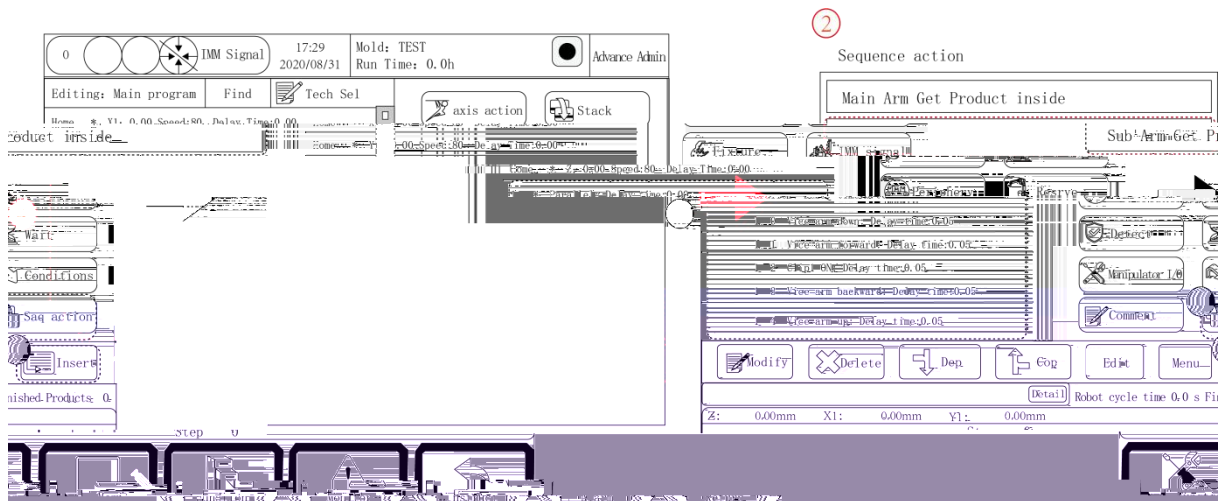
Editing: Main program	Find	Tech Sel
Home * X1: 0.00 Speed:80 Delay Time:0.00		
Home * Y1: 0.00 Speed:80 Delay Time:0.00		
Home * Z: 0.00 Speed:80 Delay Time:0.00		
* Wait: Mold Opened Limit time:50.0 Delay Time:0.00		
* Clip 1 ON: Delay time:0.00		
* Sucker1: OFF: Delay Time:0.00		
* Fixture1 BeginDetect Delay Time:0.00		
6 * Sucker1 beginDetect		
6 * Mold end: Delay		

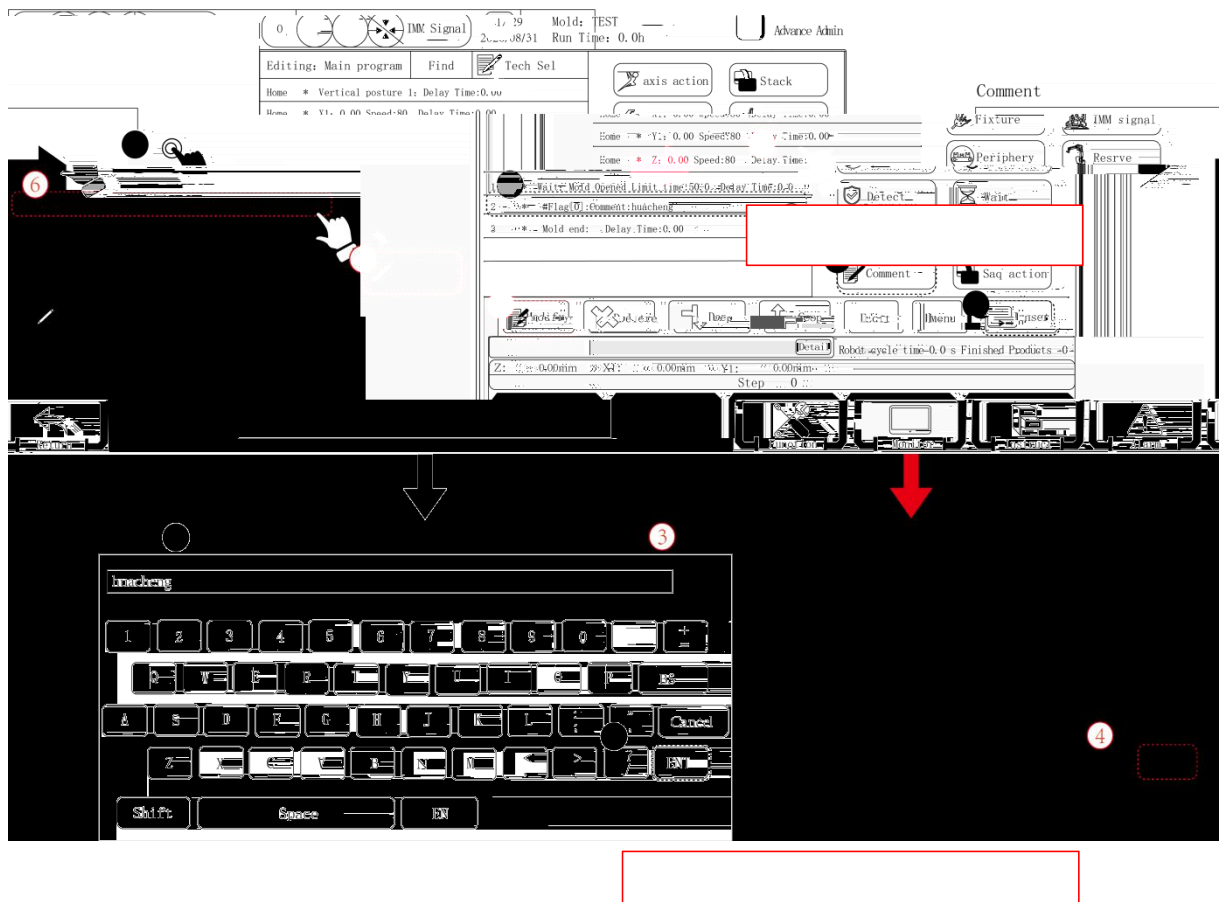


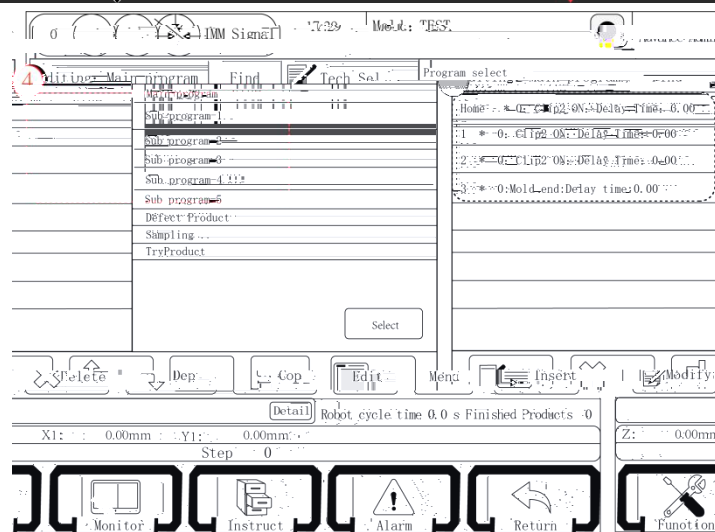
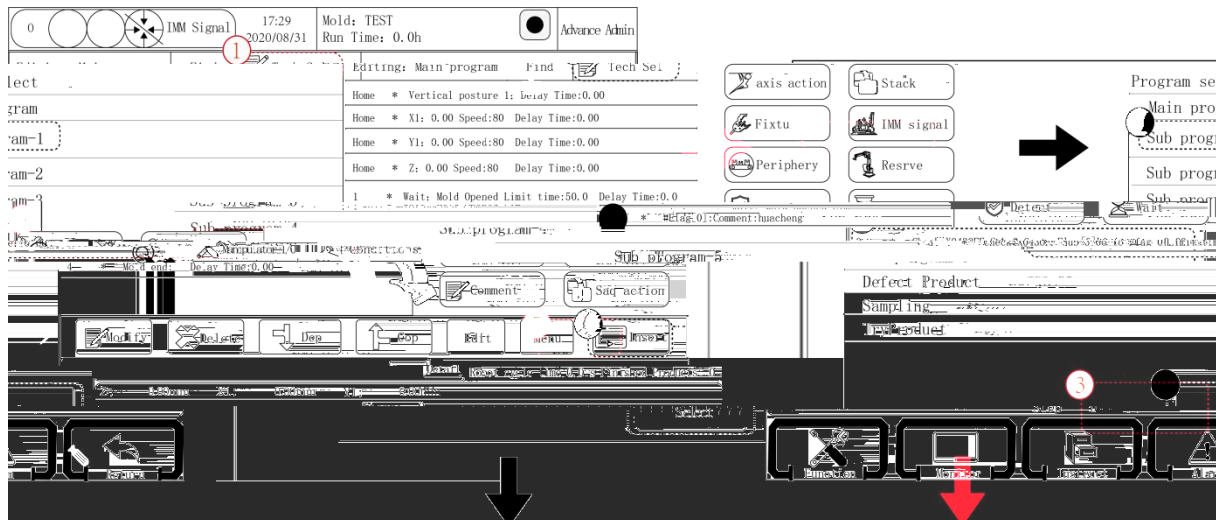


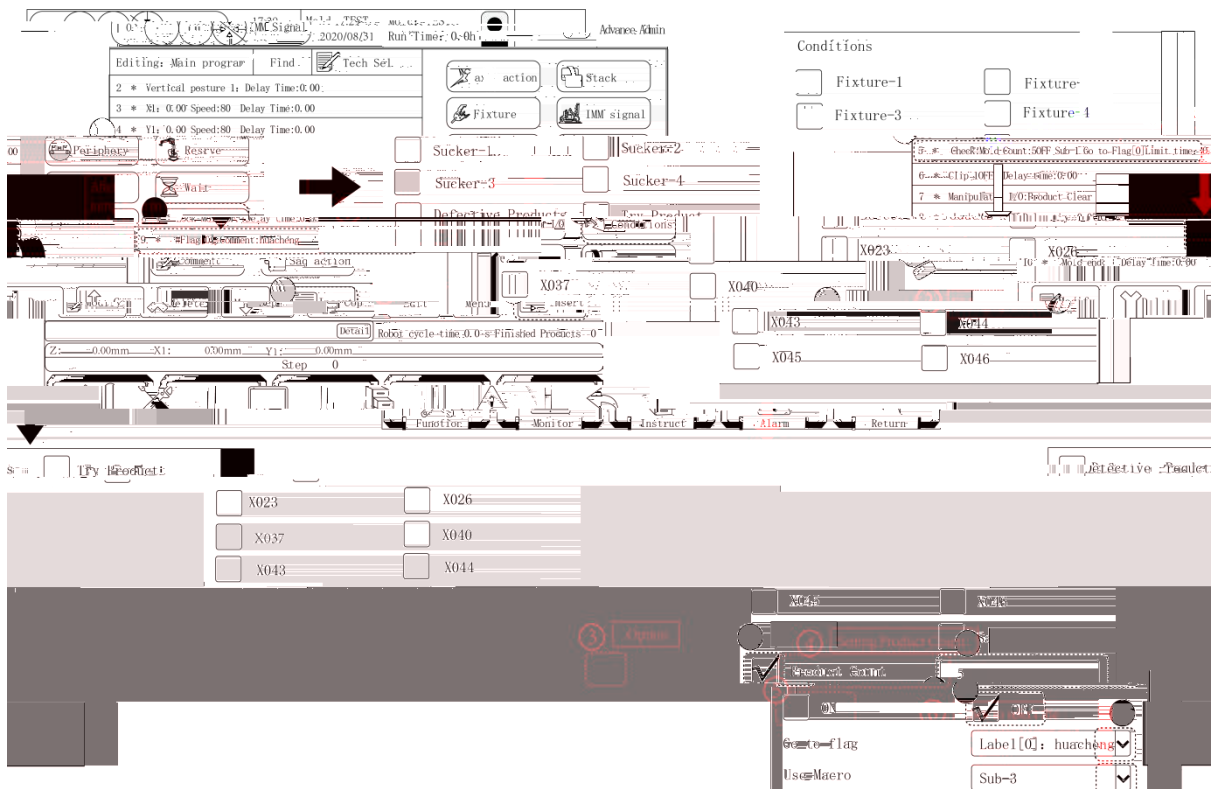
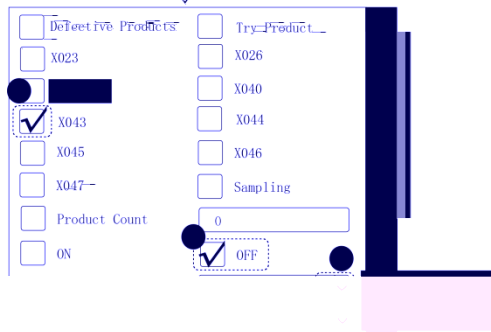
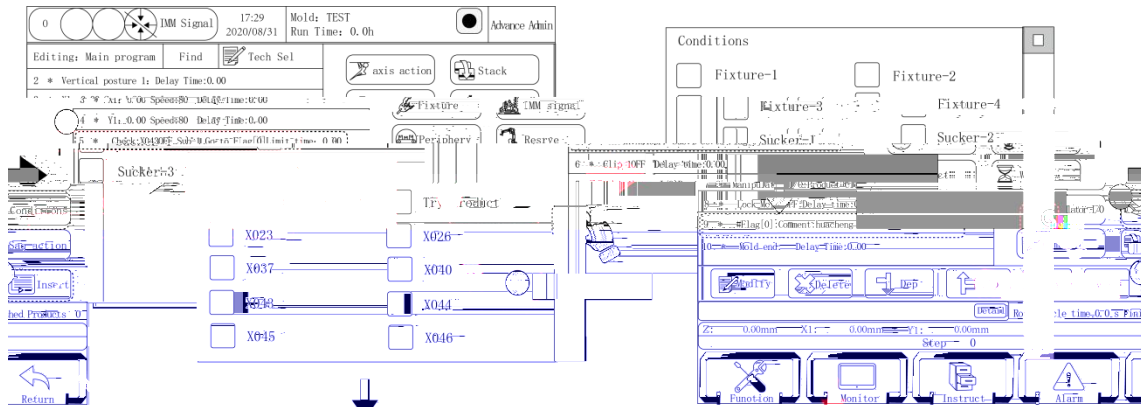




[illegible]







0

IMM Signal

17:29 2020/08/31

Mold: TEST Run Time: 0.0h

●

Advance Admin

Editing: Main program Find Tech Sel

Home	* Vertical posture 1:	Delay Time:0.00	
1	* X1: 0.00 Speed:80	Delay Time:0.00	
	* Y1: 0.00 Speed:80	Delay Time:0.00	
Home	* Z: 0.00 Speed:80	Delay Time:0.00	
1	* Wait: Mold Opened Limit time:50.0	Delay Time:0.00	
2	* Injection OFF:Interval modules:1 Action time:0.0		
3	* Wait:X017 ON Limit Time:0.5		
4	* Mold end: Delay Time:0.00		

Modify

Delete

Dep

Cop

Edit

Menu

Insert

(Detail) Robot cycle time 0.0 s Finished Products 0

Z: 0.00mm X1: 0.00mm Y1: 0.00mm

Step 0

Tool icon

Monitor

Inst. icon

Alarm

Return

axis action

Fixture

Periphery

Detect

Manipulator I/O

Comment

Sack

IMM signal

Resrve

Wait

Conditions

Saq action

Edit

Set

Custom Name

Position 1000.0 mm

Speed 80 %

Delay Time 0.00 s

☐ Early End

☐ Early Speed-Up

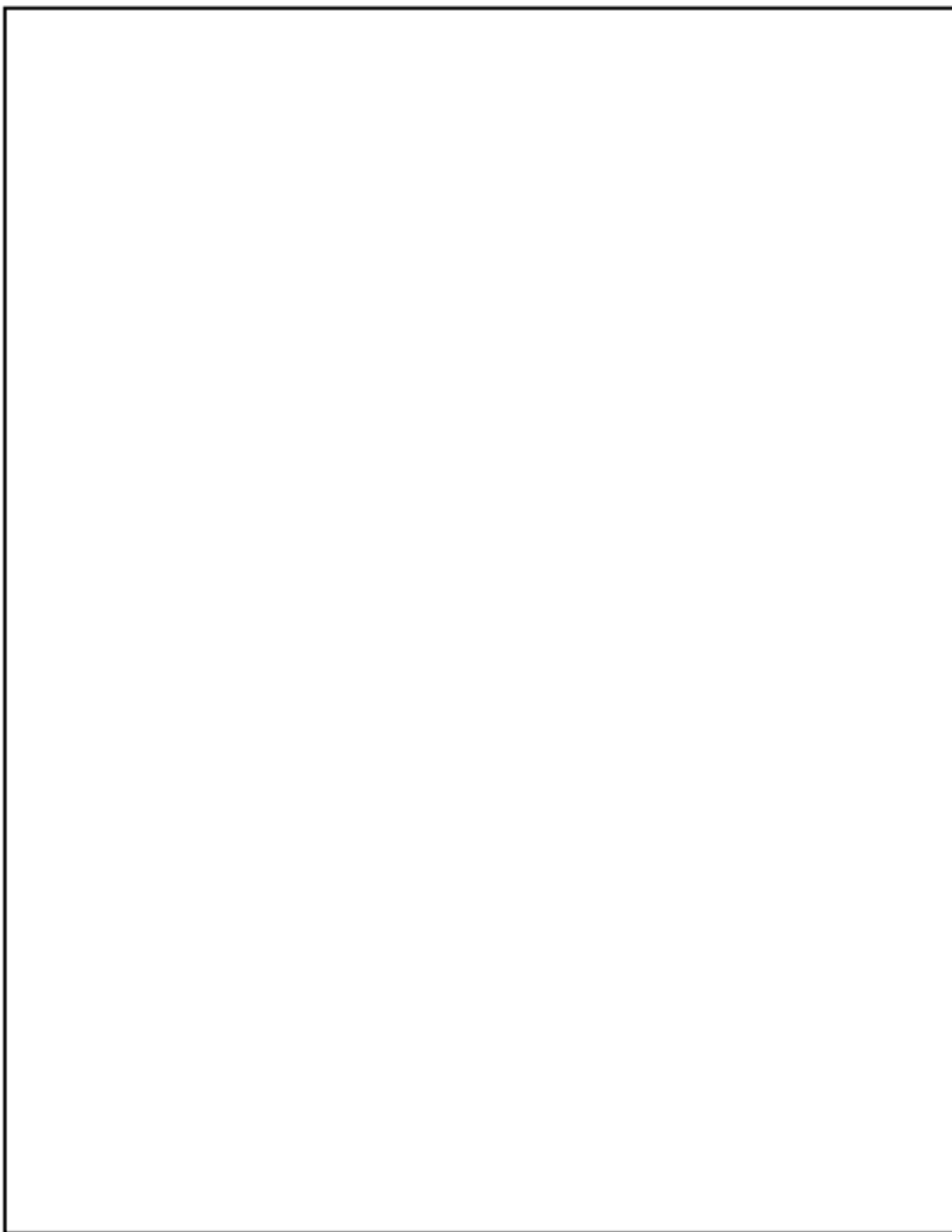
☐ Early Speed-Down 0 %

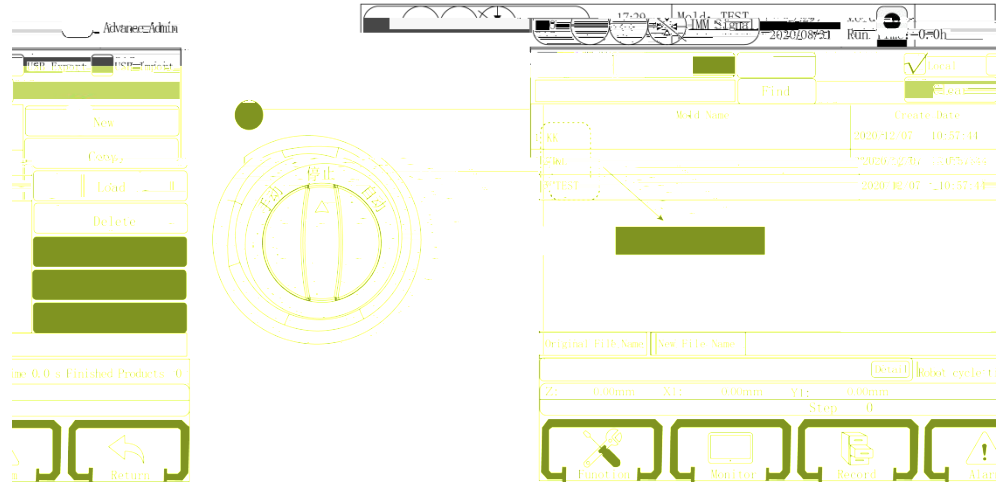
End Position 0 mm

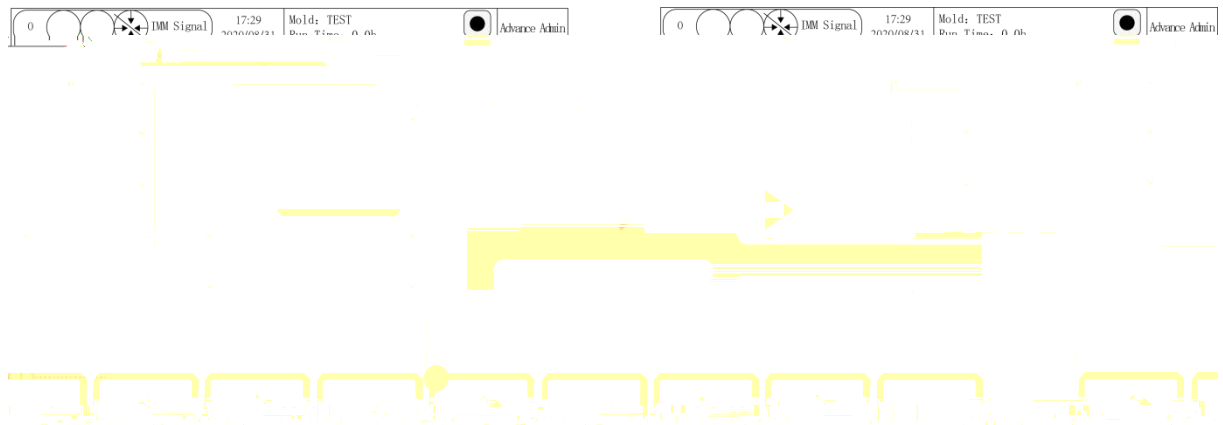
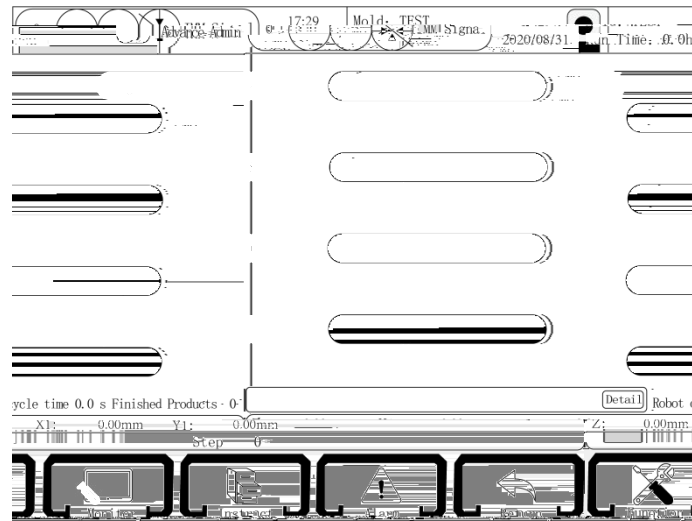
OK

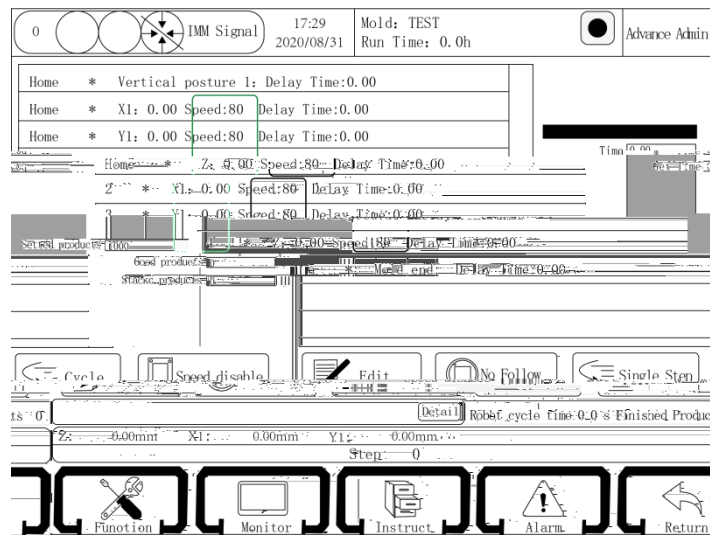
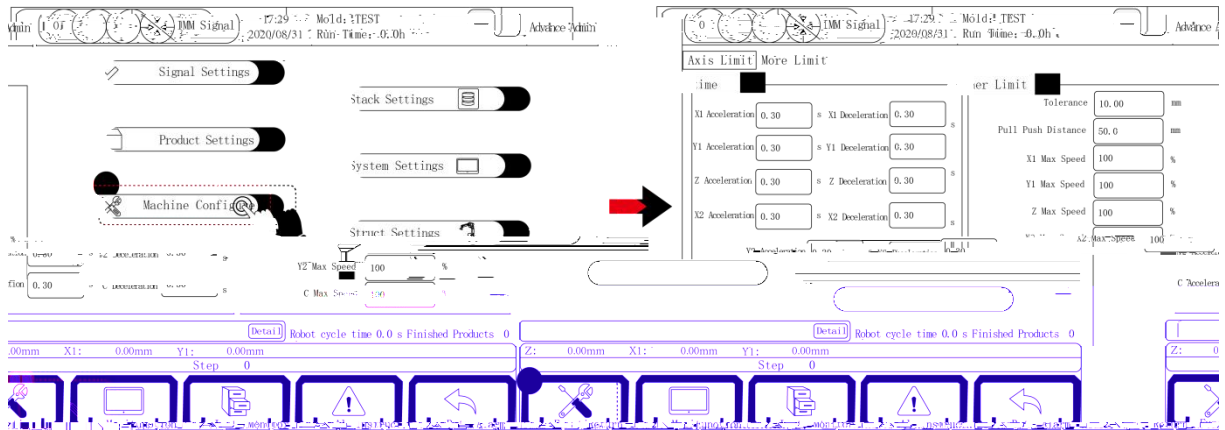
Cancel

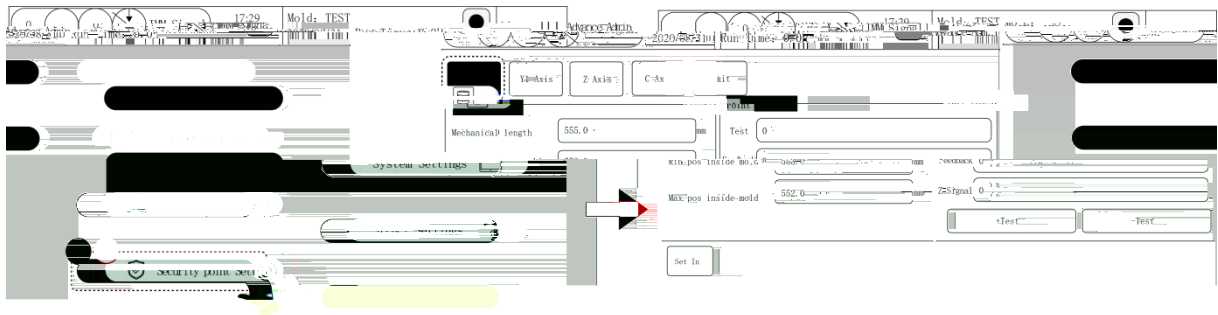
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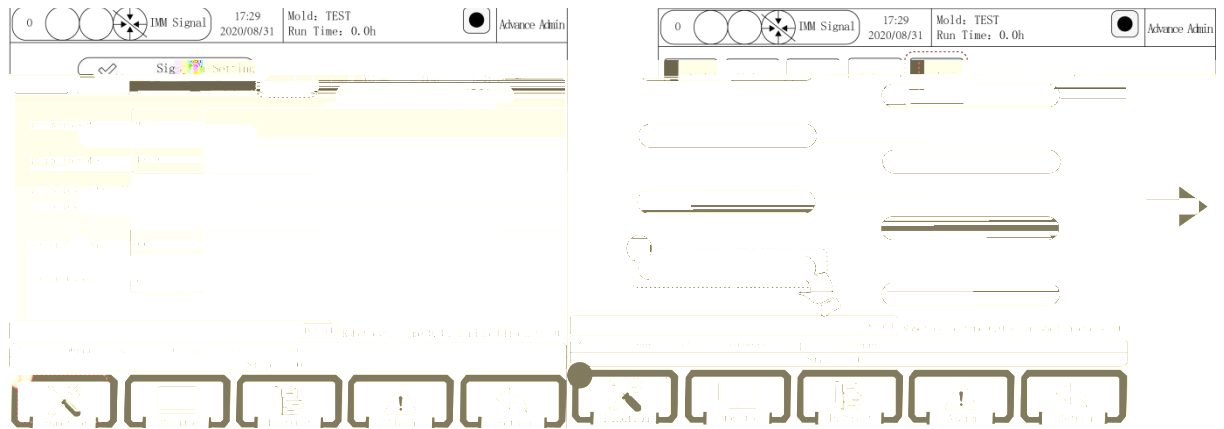






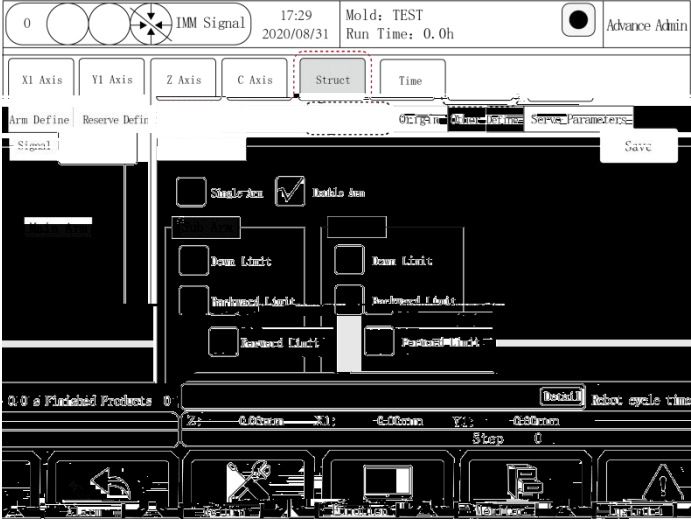






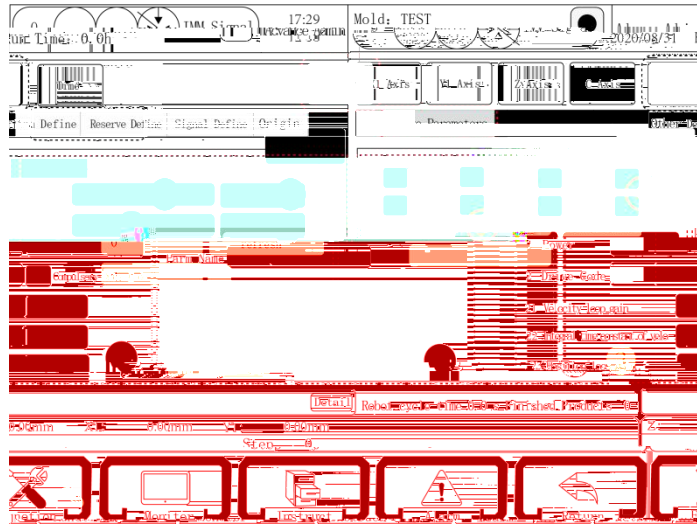
0	IMM Signal	17:29 2020/08/31	Mold: TEST Run Time: 0.0h	●	Advance Admin
Y1 Axis Y1 Axis Z Axis C Axis Limit					
Security Point Mechanical length 555.0 mm Max standby pos 553.0 mm Leave origin pos 552.0 mm			Test Feedback Test 0 Feedback 0 Z Signal 0 +Test -Test		
Set In					
(Detail) Robot cycle time 0.0 s Finished Products 0					
Z: 0.00mm X1: 0.00mm Y1: 0.00mm Step 0					
					

0	IMM Signal	17:29	Mold: TEST	●	Advance Admin
Y1 Axis C Axis Limit					
Mechanical length 2130.0 mm Internal Security zone 300.0 mm External Security zone 900.0 mm			Test 0 Feedback 0 Z Signal 0 -Test +Test		
Set In					
Robot cycle time 0.0 s Finished Products 0 (Detail) Robot cy					
Z: 0.00mm X1: 0.00mm Y1: 0.00mm Step 0					
! Alarm ↶ Return ✂ Function 📺 Monitor 📖 Instruct					

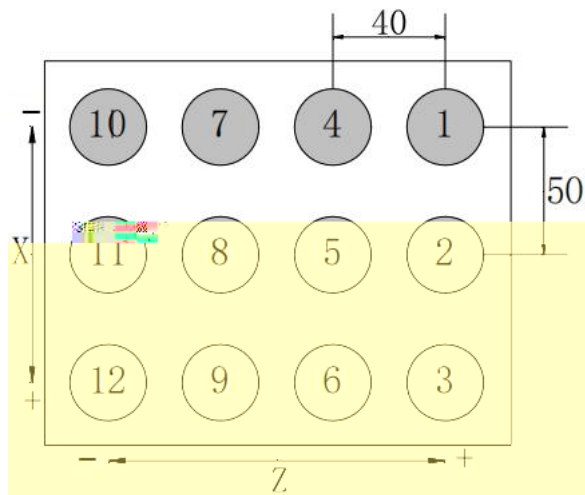


0		IMM Signal	17:29 2020/08/31	Mold: TEST Run Time: 0.0h		Advance Admin
X1 Axis	Y1 Axis	Z Axis	C Axis	Struct	Time	
Axis Time Reserve Define Signal Define Origin Other Define Servo Parameters						
Origin Sequence				Origin Setting		
1 C	4	7 Y2	Sias Servo Start Origin Set Origin Return Origin			
2	5 Z	8				
3 X2	6 Y1					
Origin Offset Z-Offset Axis Limit Velocity Acceleration Deceleration Position						
Z-0.00mm X1: 0.00mm Y1: 0.00mm Robot cycle time: 0.0s Finished: 0.0s						
Stop 0						



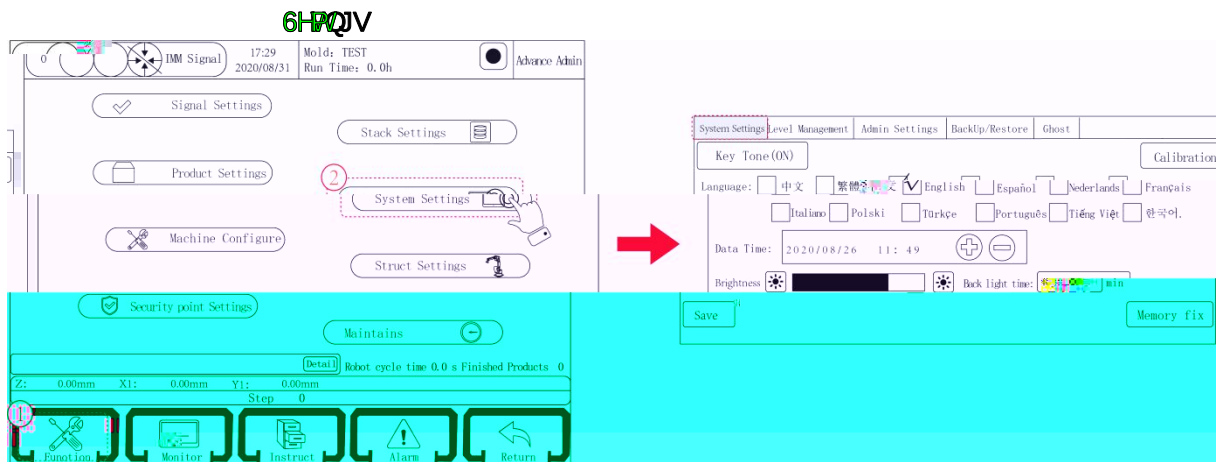


WAF)e



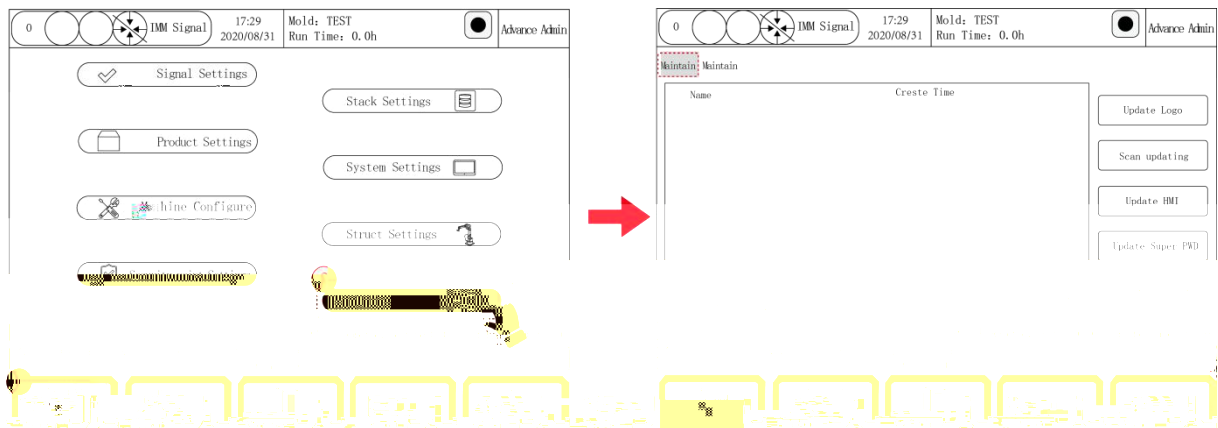
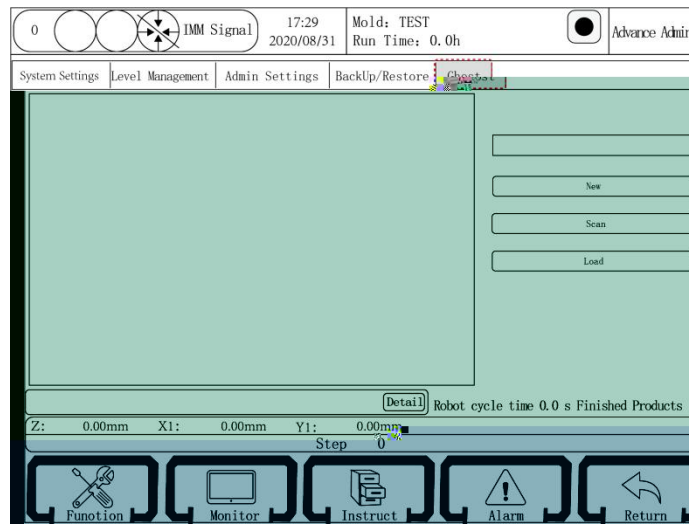
0		IMM Signal	17:29 2020/08/31	Mold: TEST Run Time: 0.0h		Advance Admin
Group-1	XZ Free Stack					
Group-2	Point Count	5				
Group-3	Current Point	- 1 +				
Group-4	X	0.0 mm				
Group-5	Z	0.0 mm				
Group-6	☒ Is Main Arm ☐ Is Sub Arm					
Group-7	Count Way	All GOOD Stack-1 Stack-2 Stack-3 Stack-4 Stack-5 Stack-6 Stack-7				
Z: 0.00mm		X1: 0.00		Y Lattice 2 Step 10.0 mm Direction ☒ PP ☐ RP Sequence ☐ XZ->Y ☒ Y->X1		
Detail Robot cycle time 0.0 s Finished Products 0				0.00mm Step 0		
Function		Monitor		Instruct		Alarm
				Return		



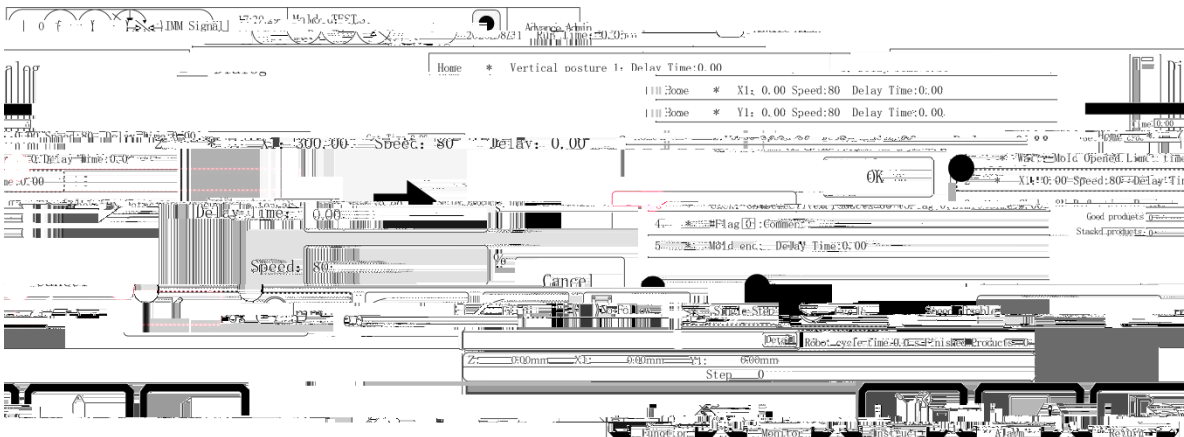
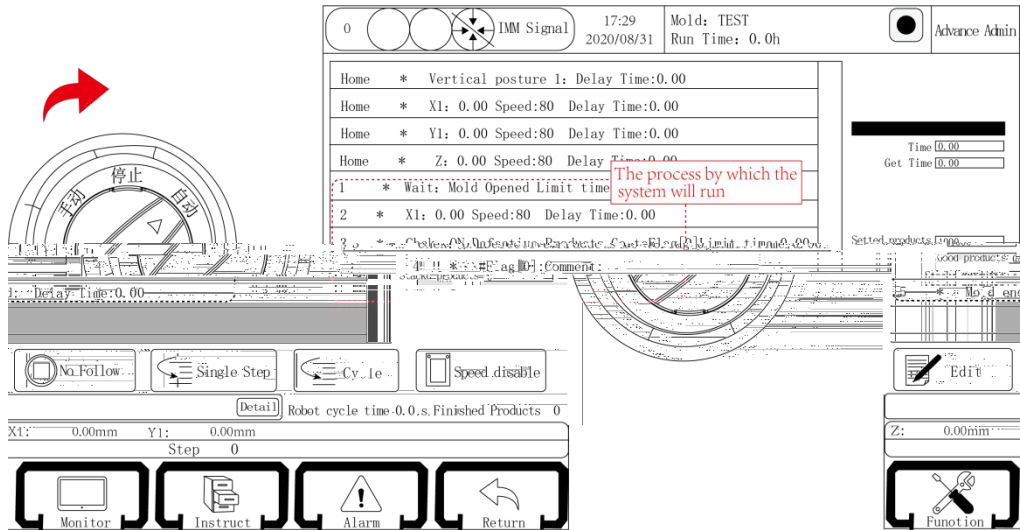


0	IMM Signal	17:29 2020/08/31	Mold: TEST Run Time: 0.0h	Admin
System Settings Level Management Admin Settings Backup/Restore Ghost				
Verify Extent Function ☐ Use Quick Guide ☐ Use Register function ☒ Use Register MachineCode: Generate Register Register RestTime: ON Limit Verify Detail Robot cycle time 0.0 s Finished Products				
Z: 0.00mm X1: 0.00mm Y1: 0.00mm Step 0				
Function Monitor Instruct Alarm Return				

0	IMM Signal	17:29 2020/08/31	Mold: TEST Run Time: 0.0h	Admin
System Settings Level Management Admin Settings Backup/Restore Ghost				
Backup Machine Configures Backup System Configures Backup All Umount Restore Machine Configures Restore System Configures Restore All				
Z: 0.00mm X1: 0.00mm Y1: 0.00mm Step 0				
Function Monitor Instruct Alarm Return				









☐ Alarm Details
 ? ✕

Alarm ID:

500

Alarm Text:

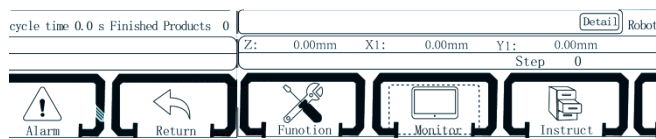
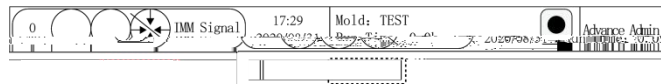
Lost contact with MainCtrl!

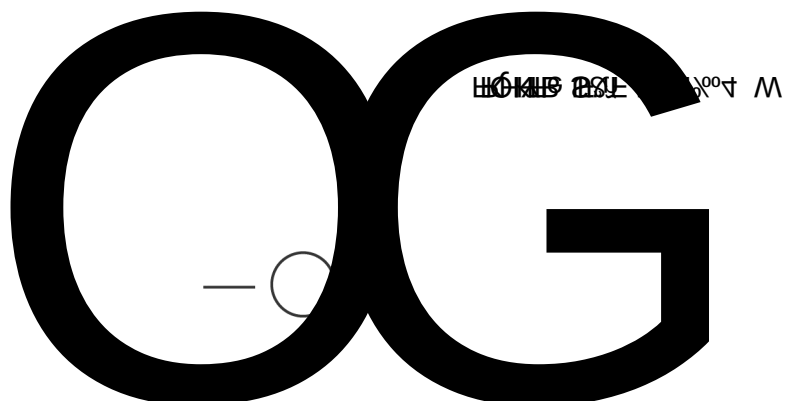
Alarm Reason:

The mainbosrd and hand control communication

Alarm Solution:

1.Please check whether there is any loose on the handheld and the connection between the host
 2.Replace the mainboard
 3.Replace the hand control

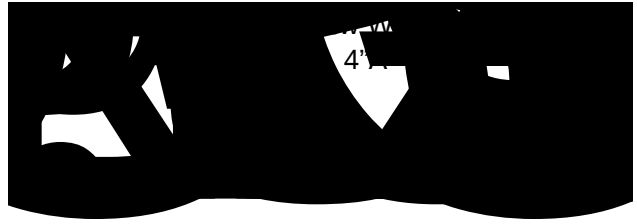




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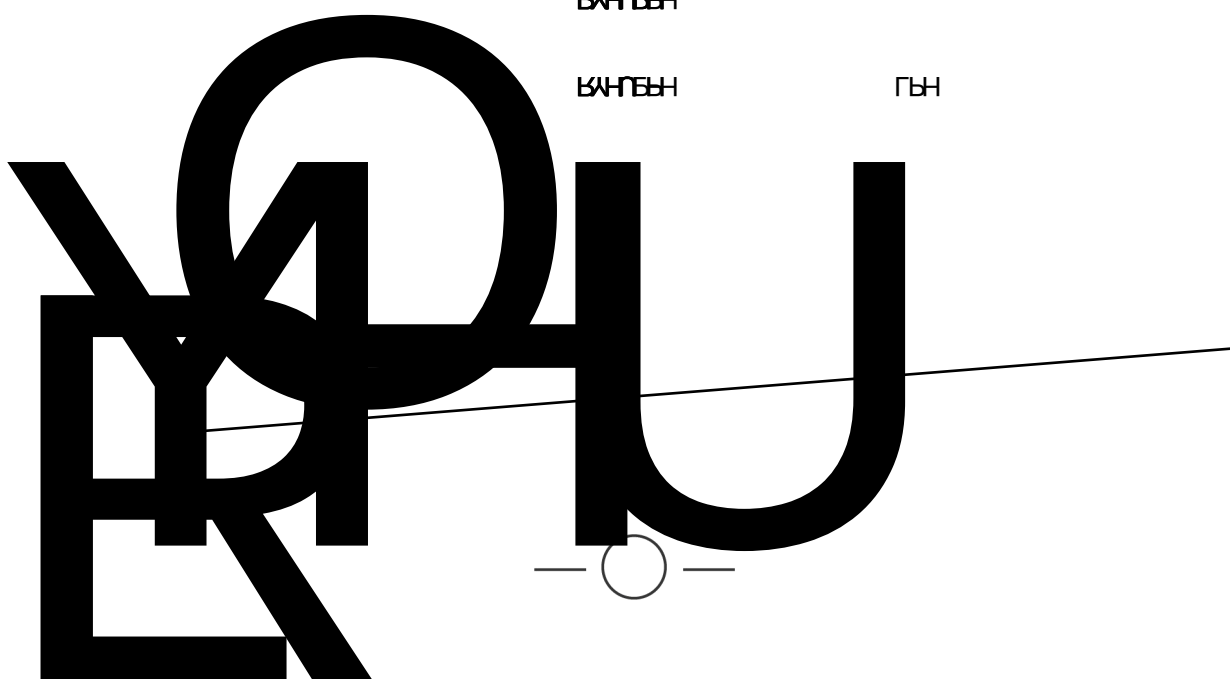
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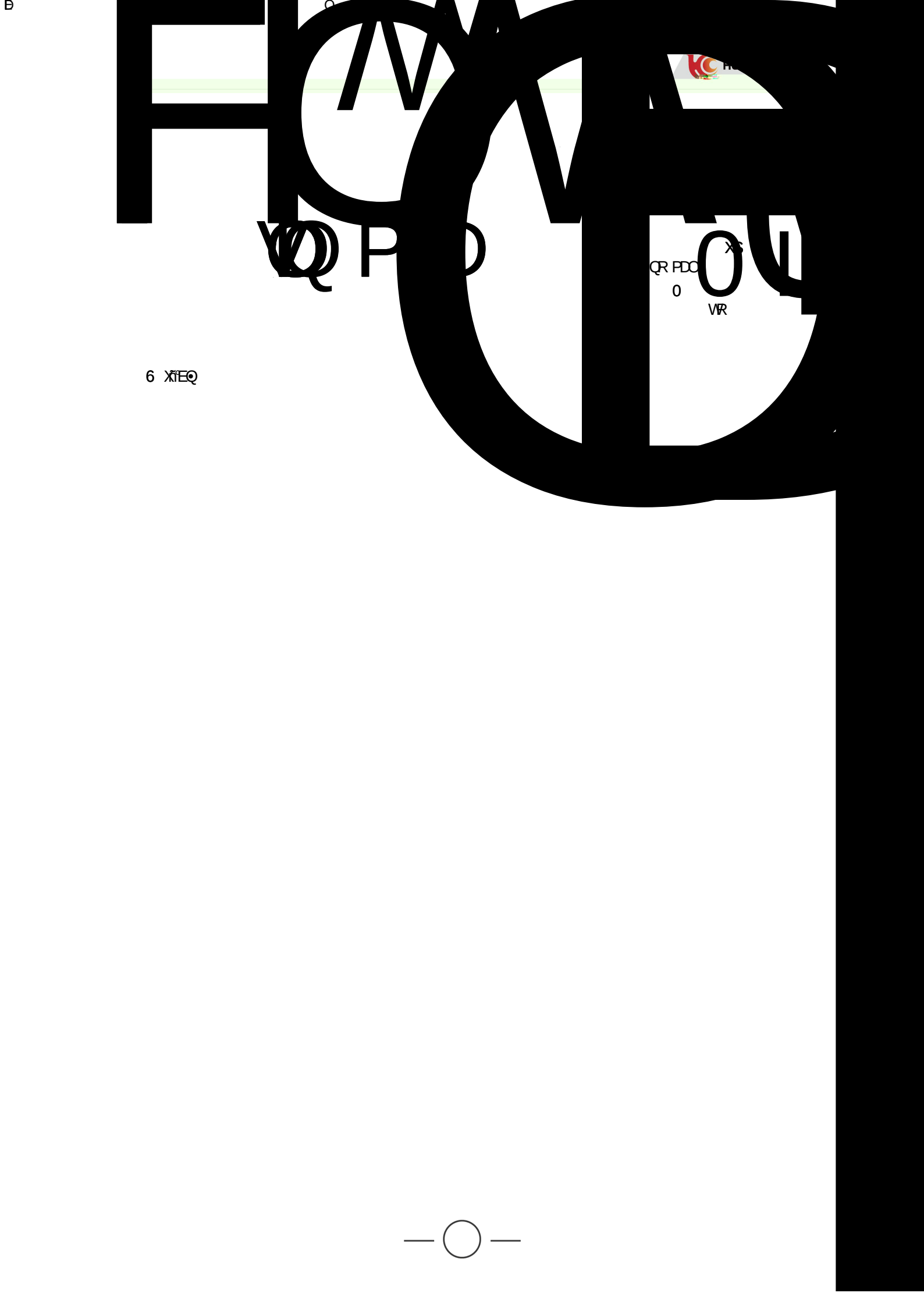
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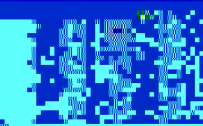




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